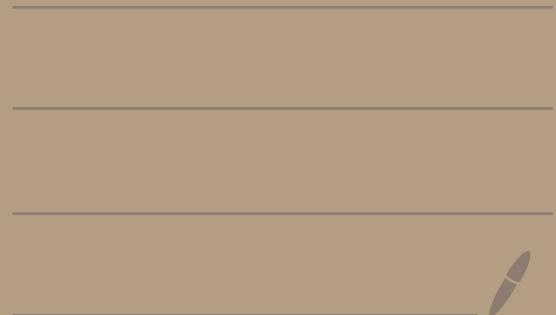


# Ingineria Calculatoarelor

---

## Toleranță la defecte pentru sisteme software



## Toleranz für Defekte

### Defekte

- Software
- Hardware
- Design
- Operativum

Latente → Aktiv



Erosion

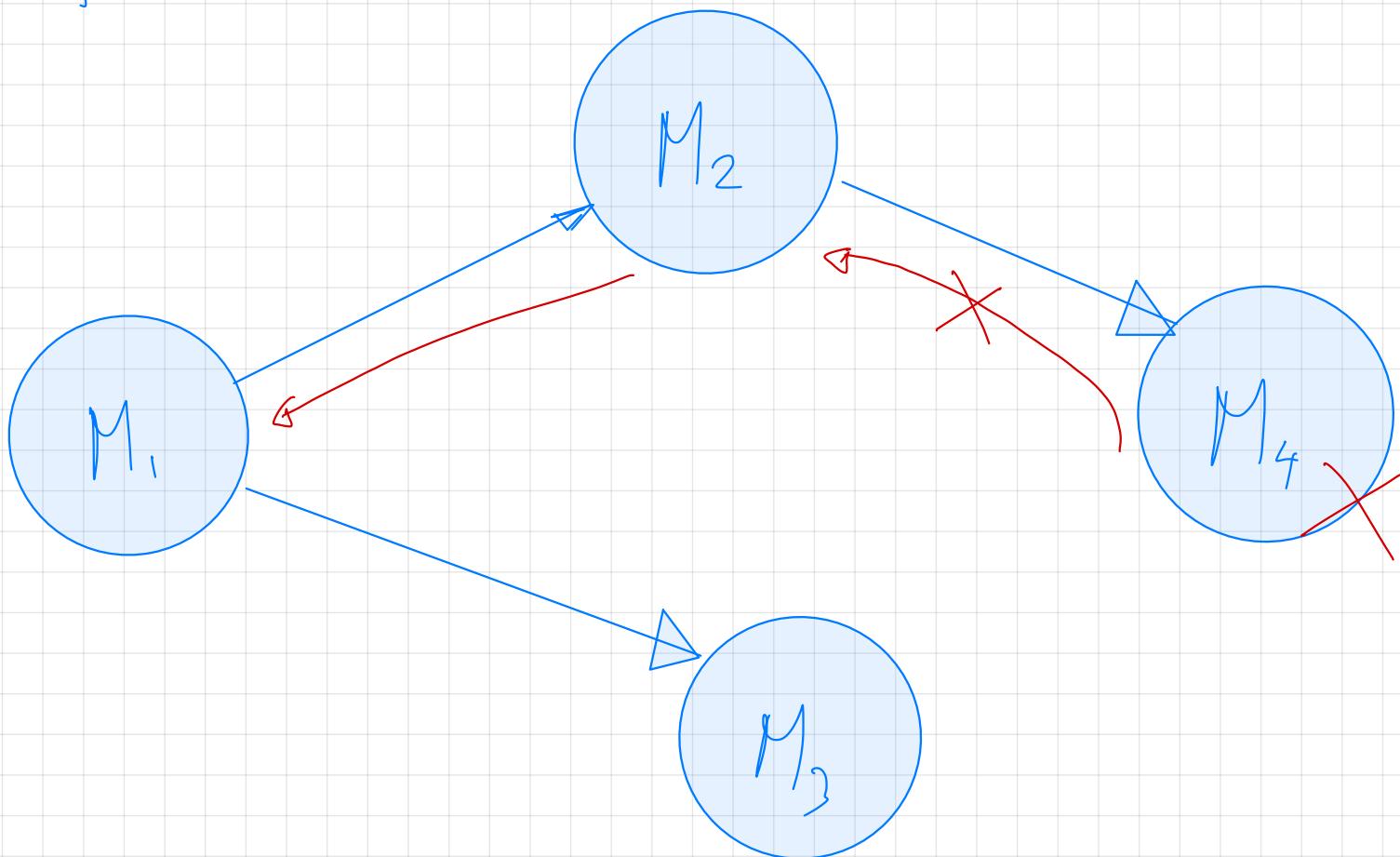


Defektionen

1. Componente me fizabile

2. ??

3. Sistem fizabil



## Example

- Bottleneck
- Routing
- Rocket loss
- Congestion collapse
- DNS

## Abonstole Risikomotiv

1. Modellzone

2. Detektore zone

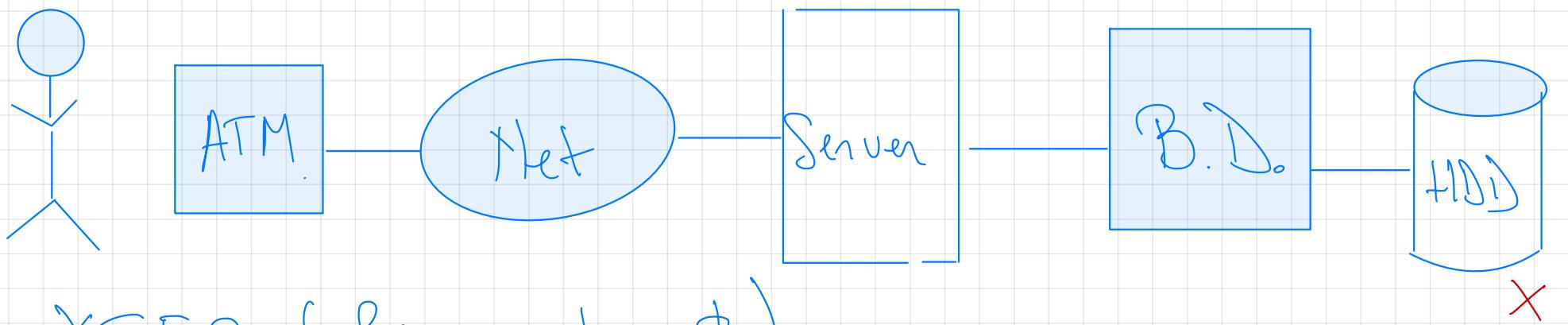
3. Moscone zone



Conform zu spezifischen

Reolumslimit

/



XFER (from, to, \$)

- Foul - stop
- foul - fast
- foul - soft
- foul - safe

## Modele

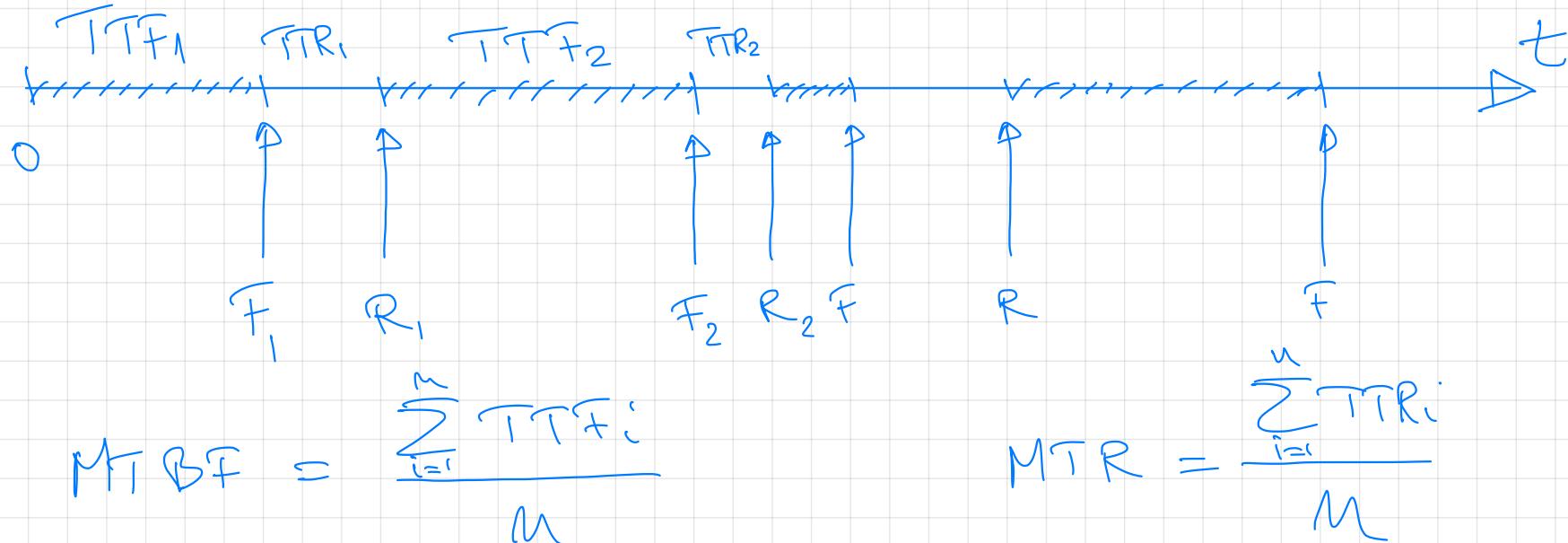
1. M. eronă folosite

2. Medie timpului de sună funcționare  
MTBF

## Disponibilitate

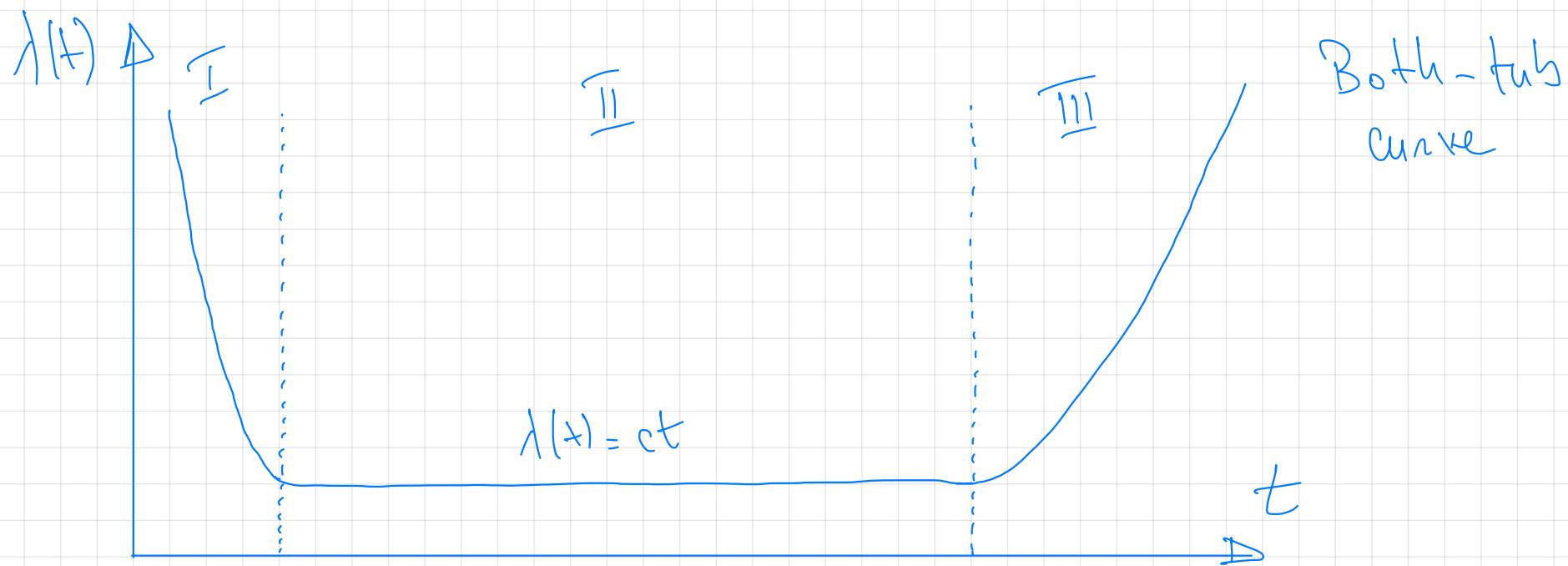
$$A = \frac{\sum TTF_i}{\sum TTF_i + \sum TTR_i}$$

$$A = \frac{MTBF}{MTBF + MTR}$$



## Intensitäts-Verteilungen

$$\lambda(t) = P(\text{fail in } [t, t+\Delta t] \mid \text{OK@}t)$$

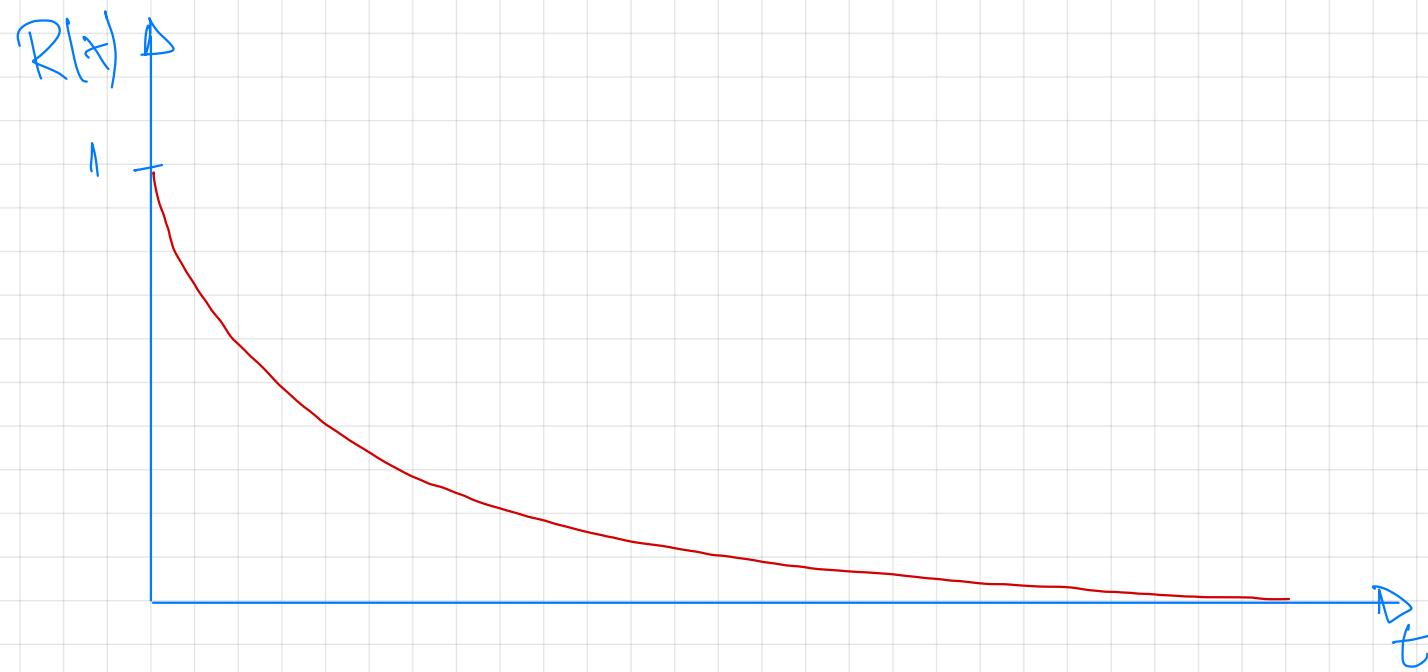


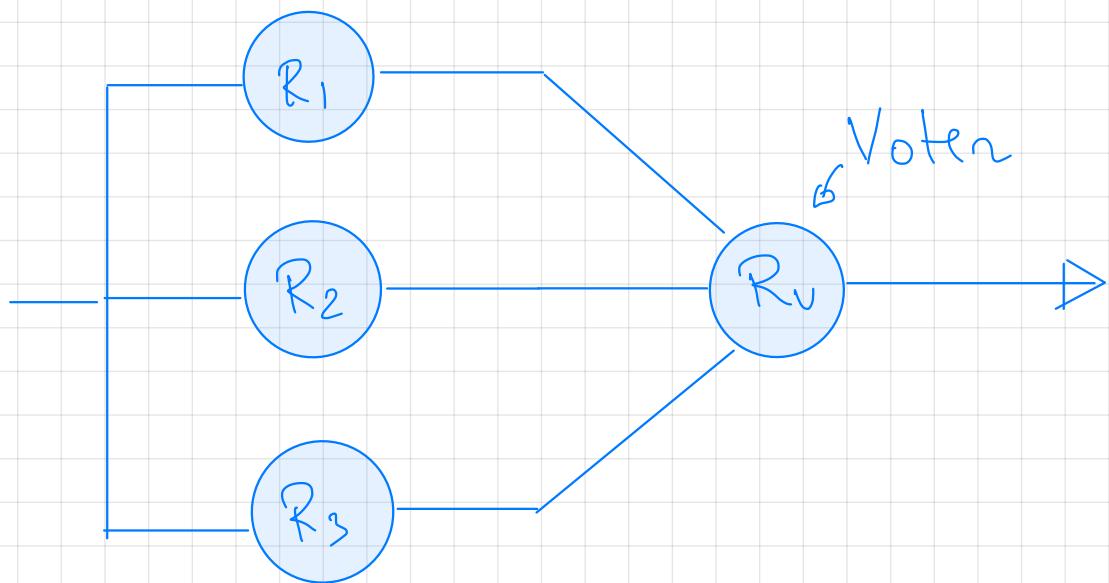
$$\lambda = \frac{1}{MTBF}$$

## Fiabilitea

$$R(t) = P(\text{OK @ time } t)$$

$$R(t) = e^{-\lambda t}$$





$$R = 10\% = 0,1$$

$$R_T = 3 \cdot (0,1)^2 - 2 \cdot (0,1)^3 = 0,03 - 0,002 = \\ = 0,028 = 2,8\%$$

$$R = 90\% = 0,9$$

$$R_T = 3 \cdot (0,9)^2 - 2 \cdot (0,9)^3 = 3 \cdot 0,81 - 2 \cdot 0,729 \\ = 0,972 = 97,2\%$$

$$R_{Total} = R_V \cdot \left( R_1 R_2 R_3 + (1-R_1) R_2 R_3 + R_1 (1-R_2) R_3 + R_1 R_2 (1-R_3) \right)$$

$$R_1 = R_2 = R_3 = R$$

$$R_V \gg R \quad R_V \approx 1$$

$$R_{Total} = R^3 + 3(1-R)R^2 = R^3 + 3R^2 - 3R^3 = 3R^2 - 2R^3$$

$$R_{Total} > R ? \quad 3R^2 - 2R^3 > R \Rightarrow 2R^3 - 3R^2 + R < 0 \Rightarrow R(2R^2 - 3R + 1) < 0$$

$$R \in [0, 1] \Rightarrow 2R^2 - 3R + 1 < 0 \Rightarrow (R-1)\left(R-\frac{1}{2}\right) < 0 \Rightarrow R > \frac{1}{2}$$

## Defectiuni

1. Replicare + Votare
2. Recuperabilitate



Nu expune o stare portișoră

XFER (From, To, \$)

Se execuție

For crash recovery

RECUPERABILITATE

"total sau niciun"

`transfer ( from_acct , to_acct , amount ) {`

`x ← read_disk ( from_acct );`

`x ← x - amount;`

`write_disk ( from_acct , x );`

`x`

`y ← read_disk ( to_acct );`

`y ← y + amount;`

`write_disk ( to_acct , y );`

`}`

`COMMIT POINT`

## Concurrenta

$$S = 1000 \quad C = 0$$

$xfer(S, c, 100) : A_1$

$A_1$  înainte de  $A_2$

$xfer(S, c, 200) : A_2$

SU

$A_2$  înainte de  $A_1$

$$S = 700 \quad C = 300$$

IZOLABILITATE

## Autoritate

- Ascunzi faptul că ochiurile sunt compuse
  - Recuperabilitate + Izolabilitate
- 
- Consistență → date învățături
  - Durabilitate

TRANSACTII ← REC + IZO + CONS + DURA

## Recoverability

1. Fail - fast
2. Crash recovery
3. Restart

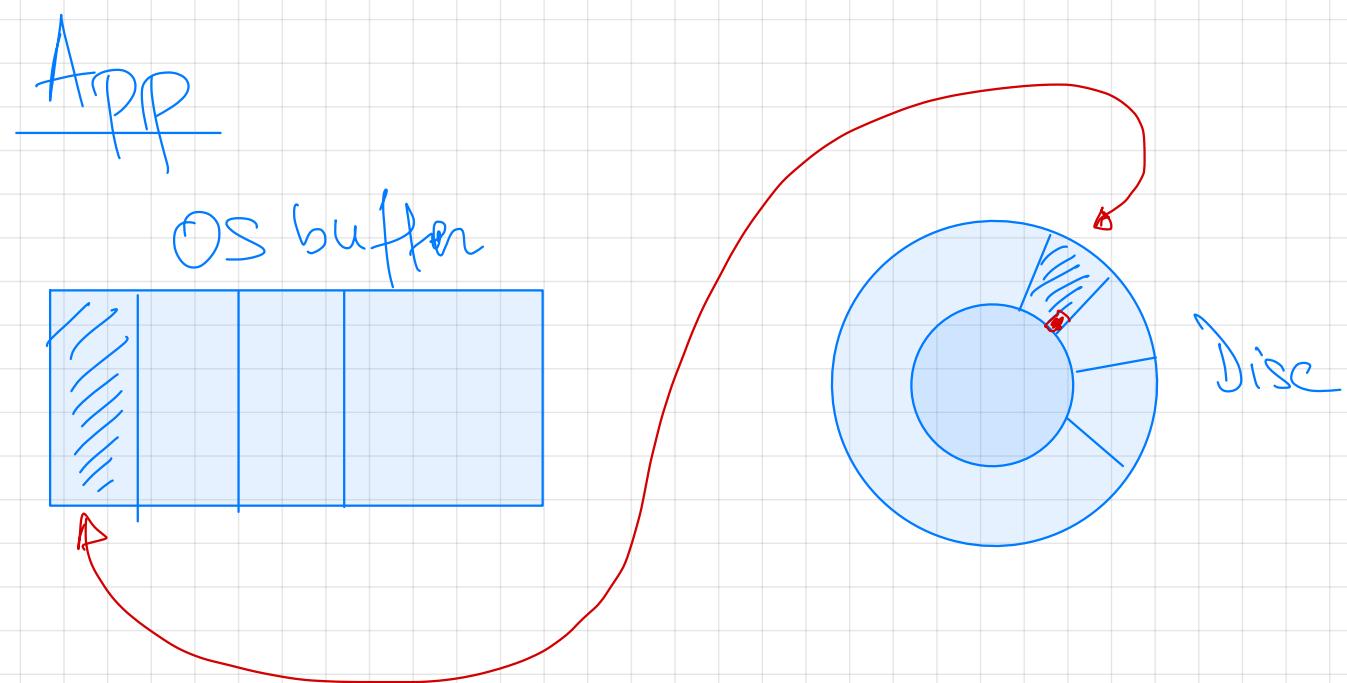
- Recoverable sector

Version history

Logging

## Model

- Foro concurrente
- Foro lwoi hardware
- Lwoi software



## Model

Confuse-put (sec, slot)

Confuse-get (sec)

Recoverable-put(sec-slot)

Recoverable-get(sec)

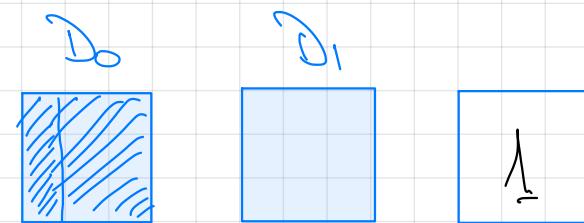
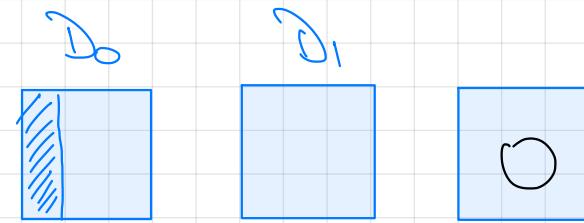
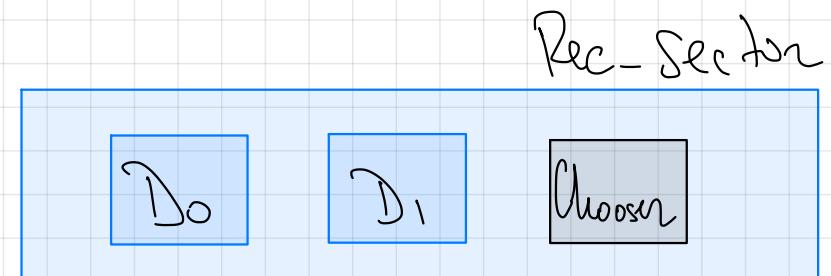
Soluție: focus copii

chosen = 0

→ scriem în  $D_0$   
→ citim din  $D_1$

chosen = 1 → citim din  $D_0$   
scriem în  $D_1$

] - eliminate toate erorile HW



```
recoverable-put (dota, mc-sector) {
```

```
    status ← conful-put (which, mc-sector.choose)
```

```
    if (status == NOT_OK) which = 0; // orbiton!
```

```
    if (which == 0)
```

```
        conful-put (dota, mc-sector.D0);
```

→ COMMIT POINT

```
else
```

```
    conful-put (dota, mc-sector.D1);
```

→ COMMIT POINT

```
    which = which XOR 1;
```

```
    conful-put (which, mc-sector.choose);
```

```
}
```

mcovable - get ( slta, mc-sector ) {

status = careful - get ( which, mc-sector. choices );

if ( status = NOT\_OK) which = 1; // arbitration!

if ( which == 0)

ols = careful - get ( slta, mc-sector.D1 );

else

ols = careful - get ( slta, mc-sector.D0 );

return ols;

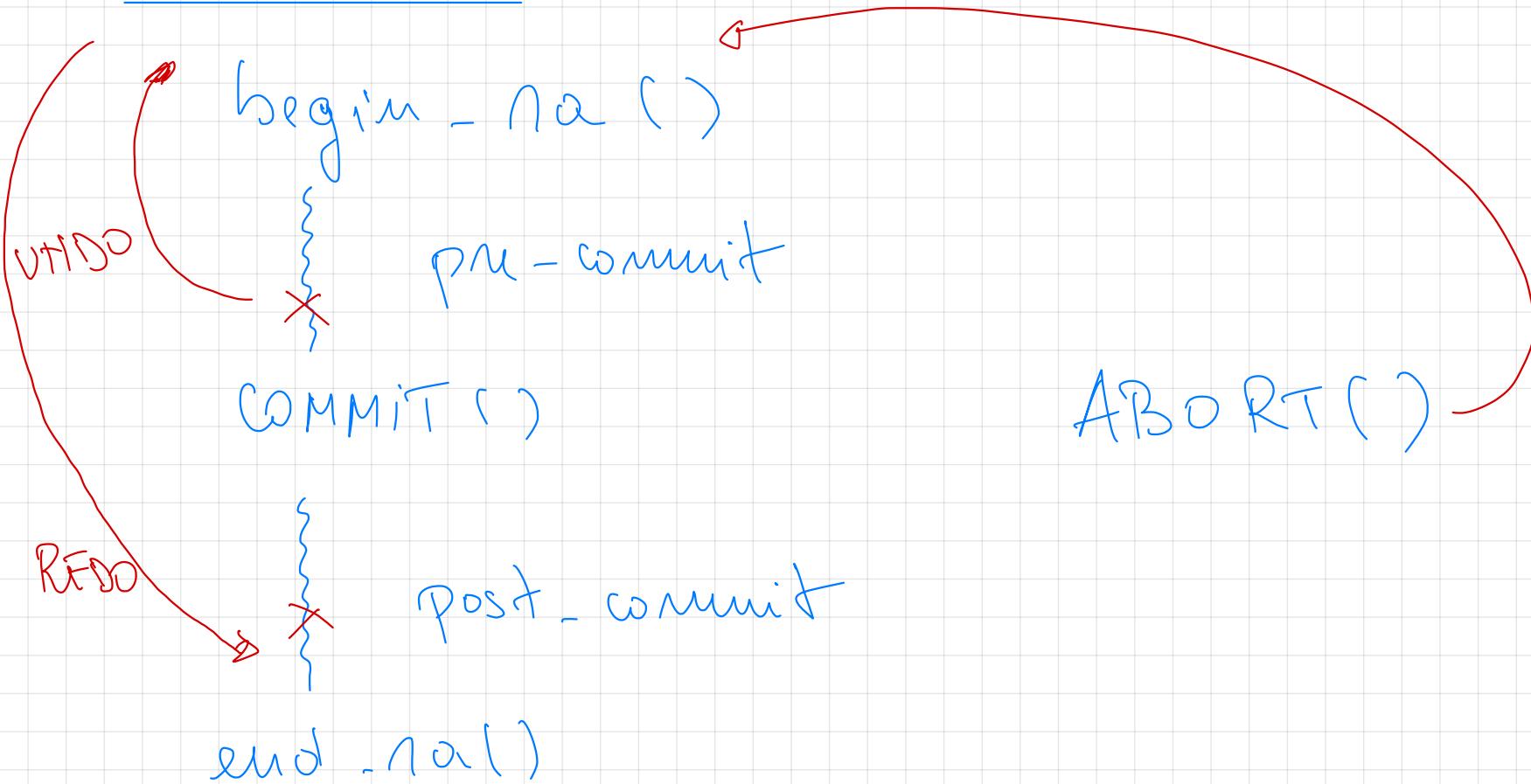
}

Commit point

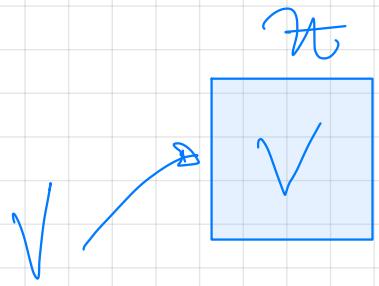
Before  $\rightarrow$  schimbarile nu sunt vizibile

After  $\rightarrow$  toate modificările sunt vizibile

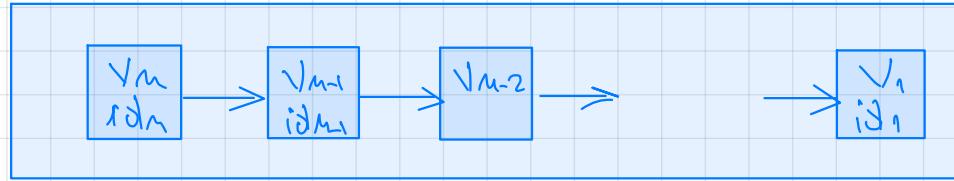
## Generalizare



Version history  
Cell Storage



Journal Storage Ht :



WriteJournal ( itemx , v , id )

ReadJournal ( itemx , id )

## Commit record table

id<sub>1</sub> ~~P~~ C

id<sub>2</sub> P

:

id<sub>2</sub> ~~P~~ A

:

LENT !

## Logging

Cell storage : Read / write

Log : store volatile si sequential

↓

CRASH RÉ.

↓

RAPID !

## Flow

1. Crash  $\rightarrow$  recovery from log
  - $\rightarrow$  uncommitted  $\rightarrow$  UNDO
  - $\rightarrow$  committed  $\rightarrow$  REDO (install in cell st.)
2. ABORT( )  $\rightarrow$  UNDO current action (REDO)

# Append-only

type : UPDATE

id ← 123

old : X → old

new : X → new

type : OUTCOME

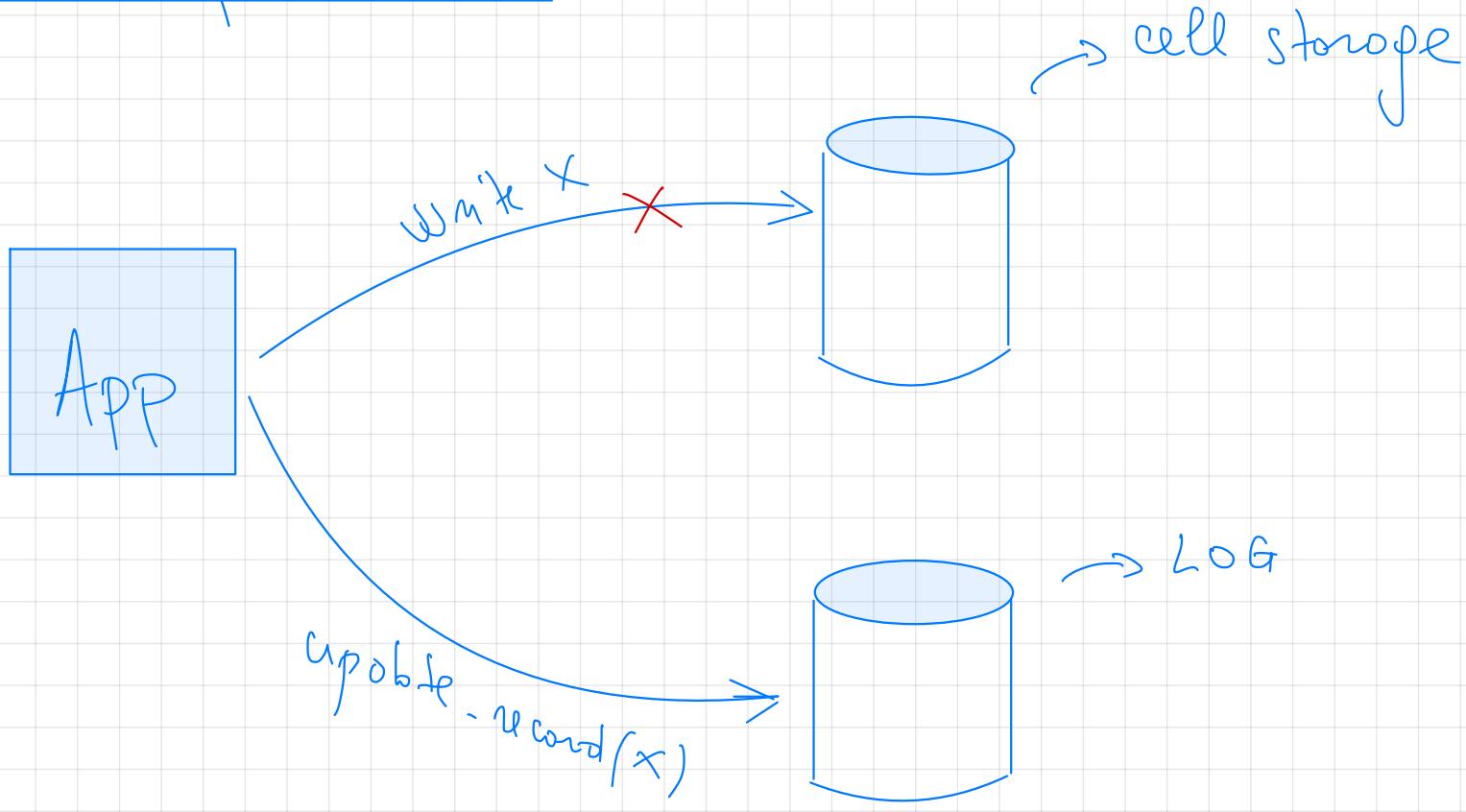
id ← 422

status : COMMITTED

1. Cmd seen in log?

2. Can from crash recovery?

## BD stores to physical disc



1. Write-ahead logging (WAL)

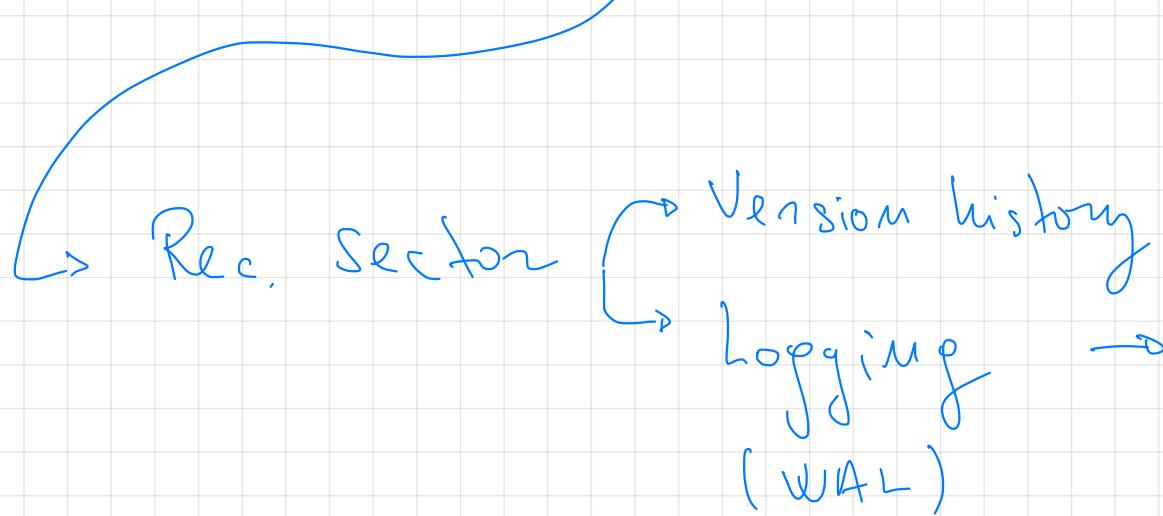
## Cross Recovery

1. Some log in some inver
2. Winners : COMMITTED & ABORTED  
Losers : anything else
3. REDO COMMITTED winners  
UNDO Losers

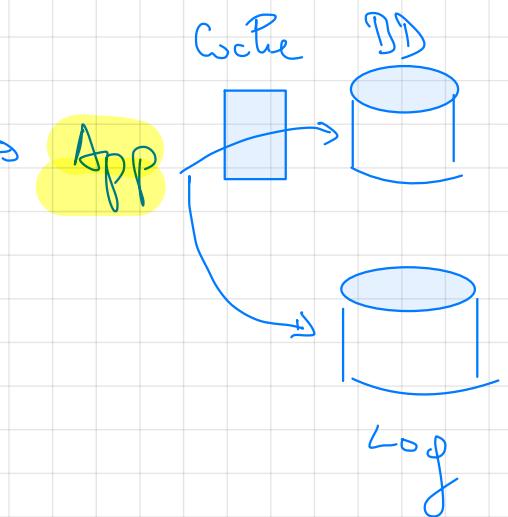
# Atomicity

Recoverability

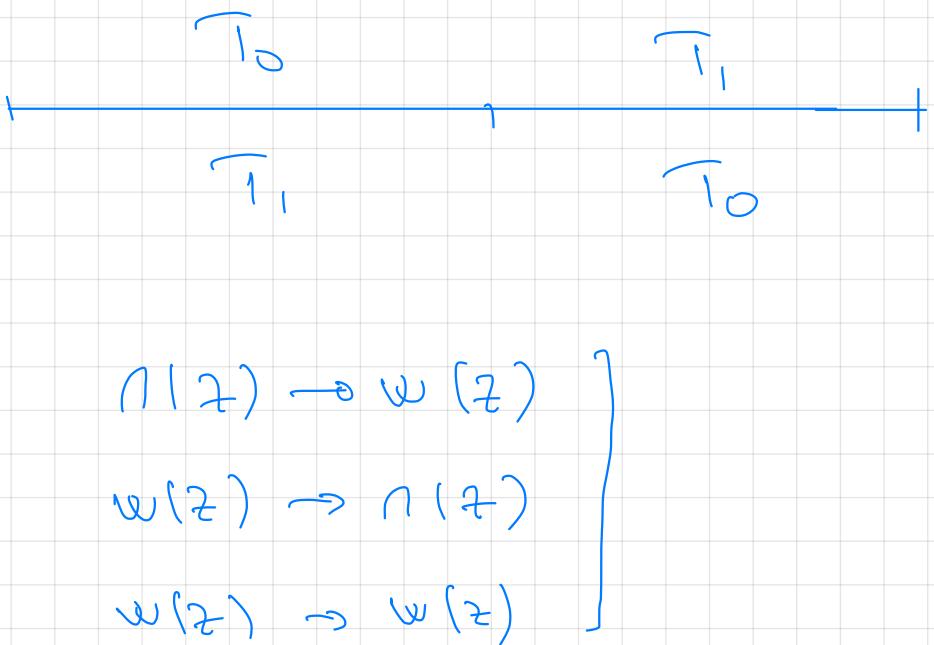
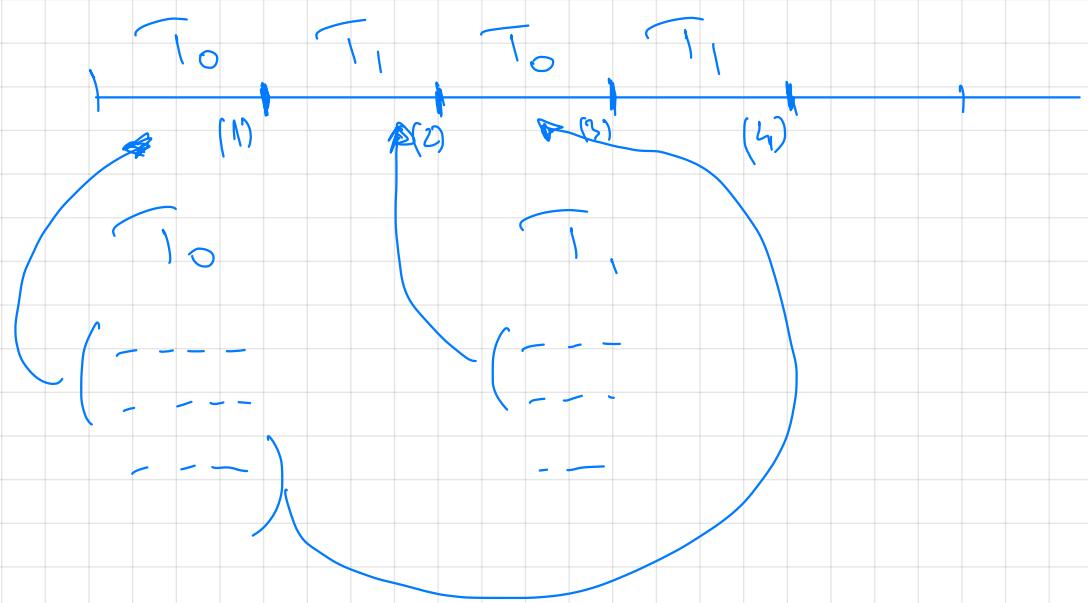
Isolation



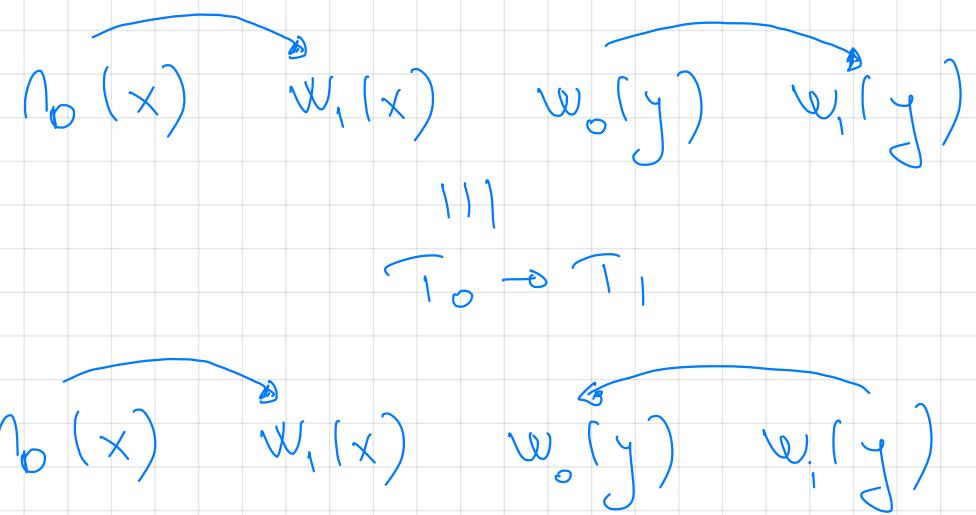
→ ABORT  
CRASH



## izolohilitote



- $\overbrace{\quad}^{T_0}$
- 1) Read  $x$
- $\overbrace{\quad}^{T_1}$
- 2) write  $x$
- 4) write  $y$
- $\overbrace{\quad}^{T_0}$
- 3) write  $y$



## Action graph

$\overline{T_1}$

$\overline{T_2}$

$\overline{T_3}$

$\overline{T_4}$

①  $\Pi_1(x)$

②  $W_2(x)$

③  $\Pi_3(y)$

④  $\Pi_4(x)$

⑤  $W_1(y)$

⑥  $W_2(y)$

⑦  $W_3(z)$

DAG

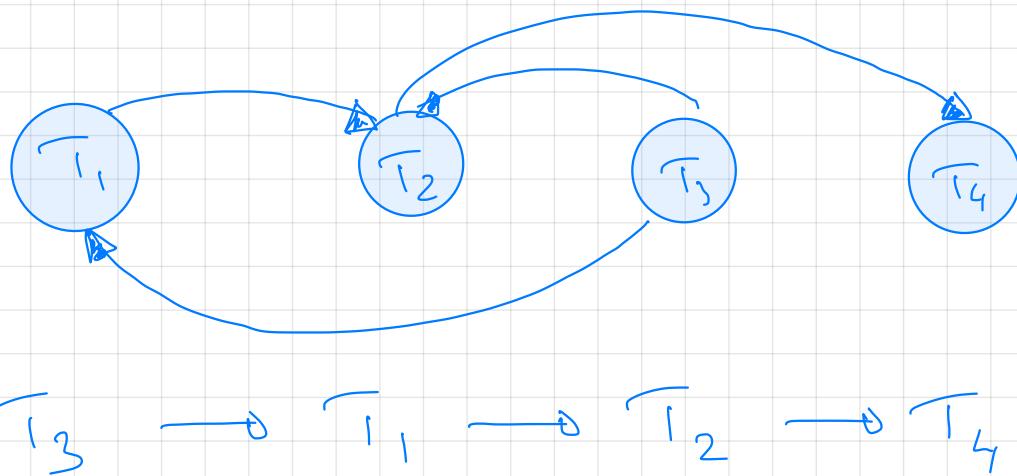
Conflicts?

$T_1 \quad T_2$

$T_1 \quad T_3$

$T_2 \quad T_3$

$T_2 \quad T_4$



$T_3 \rightarrow T_1 \rightarrow T_2 \rightarrow T_4$

$T_1$

$T_2$

$T_3$

$T_4$

①  $\lambda_1(x)$

②  $w_2(x)$

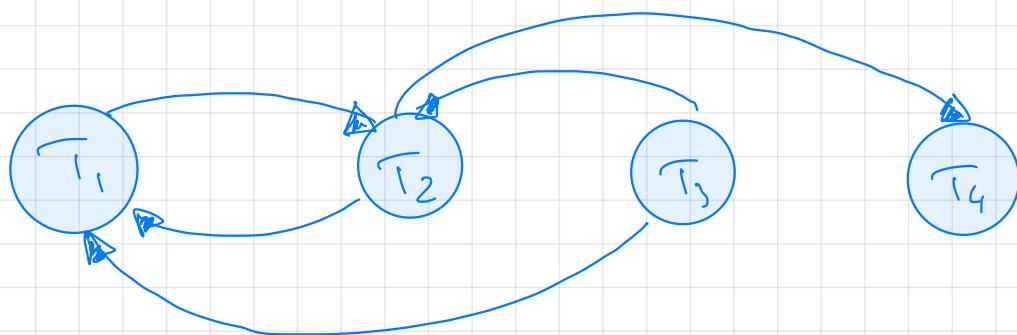
③  $\lambda_3(y)$

④  $\lambda_4(x)$

⑤  $w_1(y)$

⑥  $w_2(y)$

⑦  $w_3(z)$



Dacă Acțion graph-ul este aciclic  $\Rightarrow$

$\Rightarrow$  Acționul este serializabil  $\Rightarrow$  operațiunile sunt fizabile

Sunt topologice

# Locks

acq (x)

rel (x)

i<sub>2</sub> o OK

Re<sub>2</sub> NOIC

T<sub>0</sub>

(1) acq(x)  
    w<sub>0</sub>(x)  
    rel(x)  
    (2) acq(y)  
        w<sub>0</sub>(y)  
    rel(y)

T<sub>1</sub>

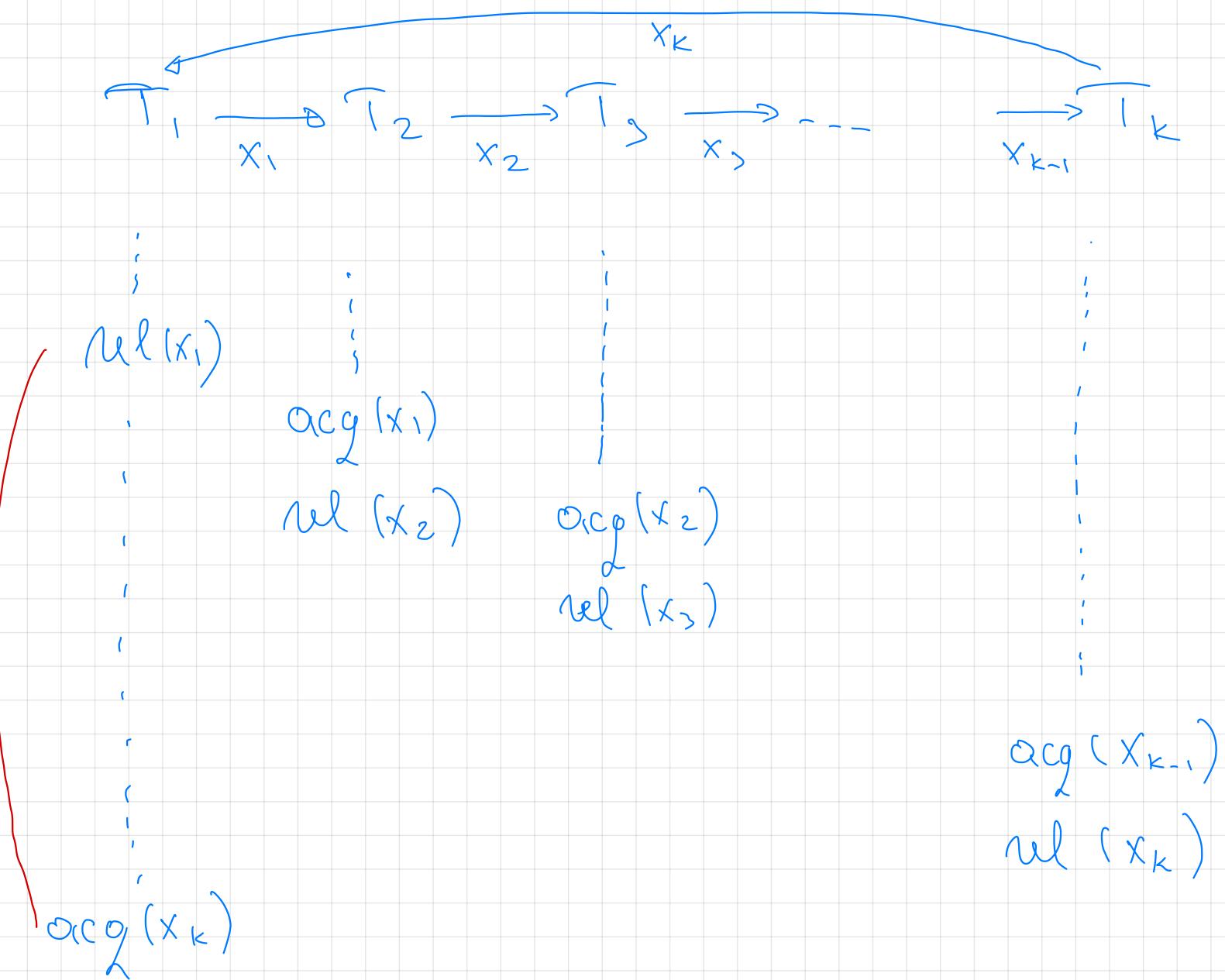
(1) acq(x)  
    w<sub>1</sub>(x)  
    acq(y)  
    (w<sub>1</sub>(y))  
    (2) rel(x)  
        rel(y)

## Two-phase locking

No release before ALL acquires!

[  
   $\text{acq}(x)$   
   $\cap(x)$   
   $\text{acq}(y)$   
   $\cap(y)$   
  ;  
    → COMMIT POINT

[  
   $\text{rel}(y)$   
   $\text{rel}(x)$

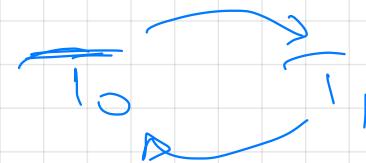


T<sub>0</sub>

acq(x)  
Mod(x)  
  
acq(y)  
Write(y)  
  
rel(y)  
rel(x)

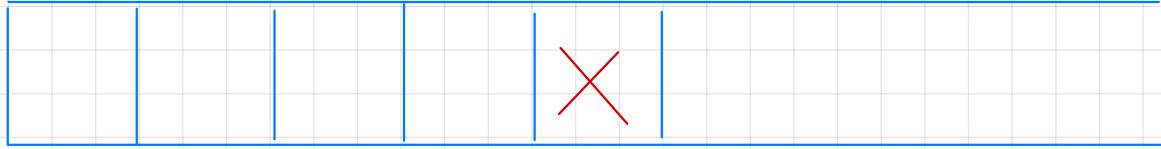
T<sub>1</sub>

acq(y)  
Mod(y)  
  
acq(x)  
Write(x)  
  
rel(x)  
rel(y)



1. Timers
2. Waits-for graph

# Logs & locks



## Aplicații

1. Transacții,

Consistency  
Durabilitate

2. Sisteme distribuite

Transacții A.C.i.D.

## Consistency sharding

Centralizaté → Multi-sharding

The diagram illustrates a sharding strategy where data is partitioned across multiple shards. Two tables are shown:

SiD	Hume	ID Fae.
35	Hlenbent	5

ID Fae.	Hume Fae.
5	A & C
6	ETT

A blue arrow points from the 'ID Fae.' column of the first table to the 'ID Fae.' column of the second table, labeled 'P.K.' above it. A yellow circle highlights 'P.K.'.

Distribuit

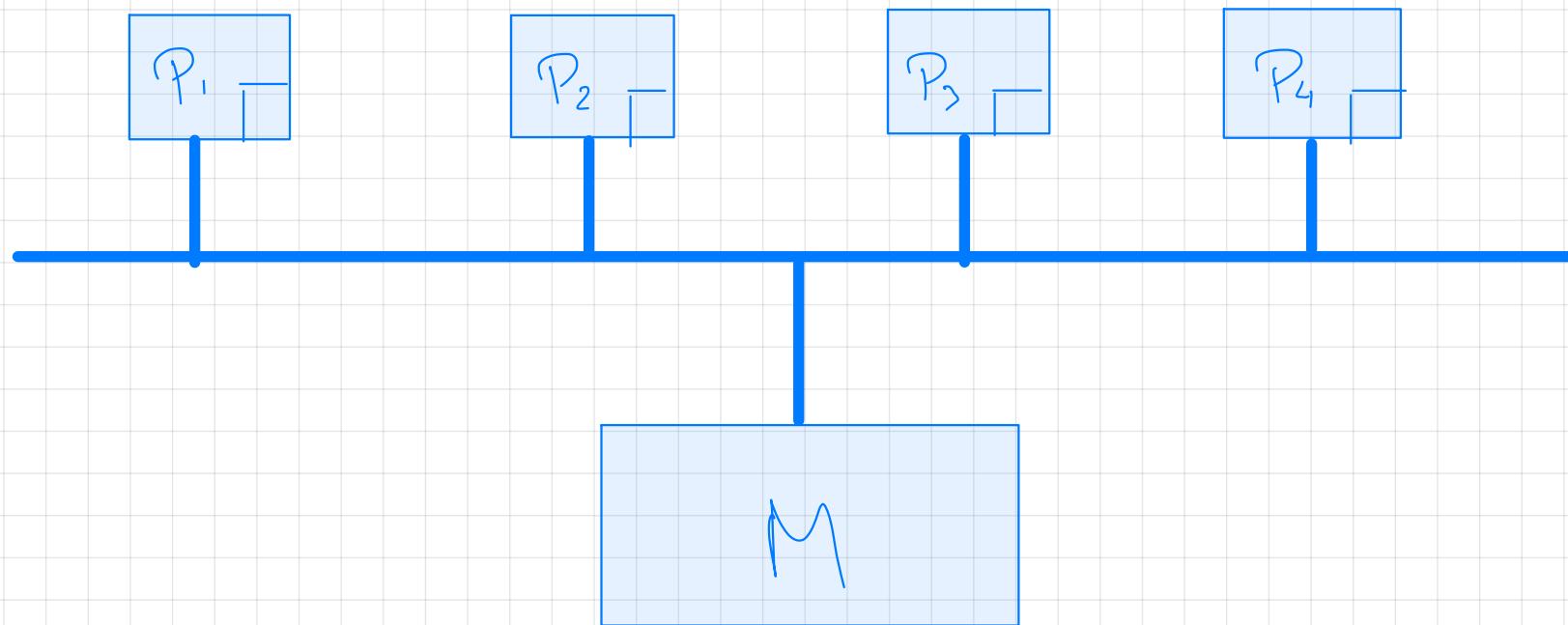
DNS - Expiration time

Web caches - "if modified since"

" ] Weak Cons.  
] Eventual Cons.

## Strong Consistency

O cînd în toate interacțiunile rezultatul ultimei acțiuni



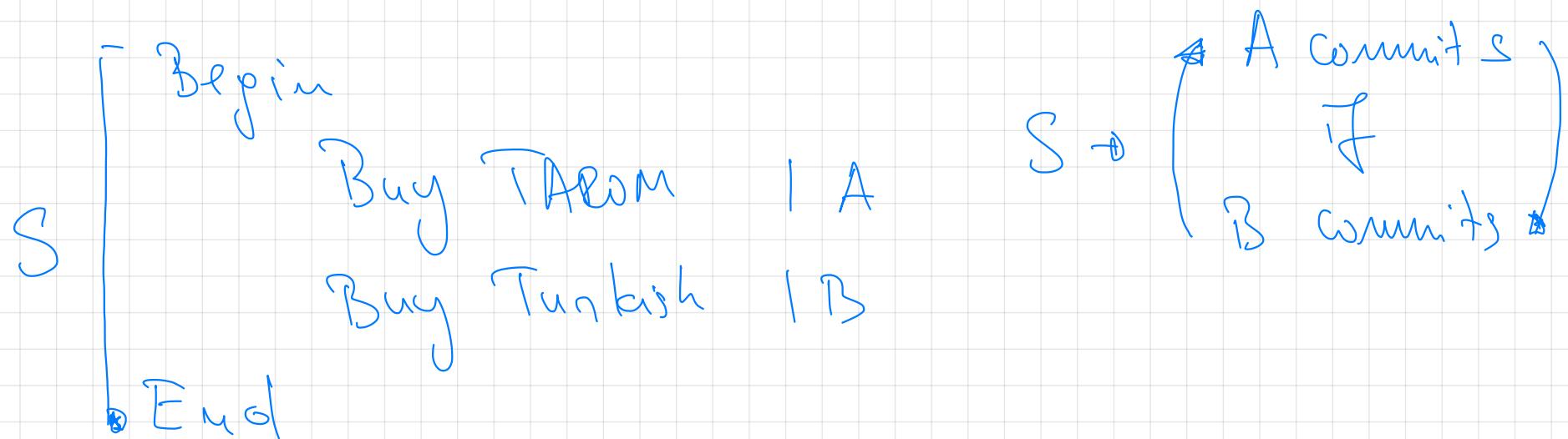
1. Write-thru cache

2. Snoopy cache

## Multi-site Atomicity



## Nested Atomic Action



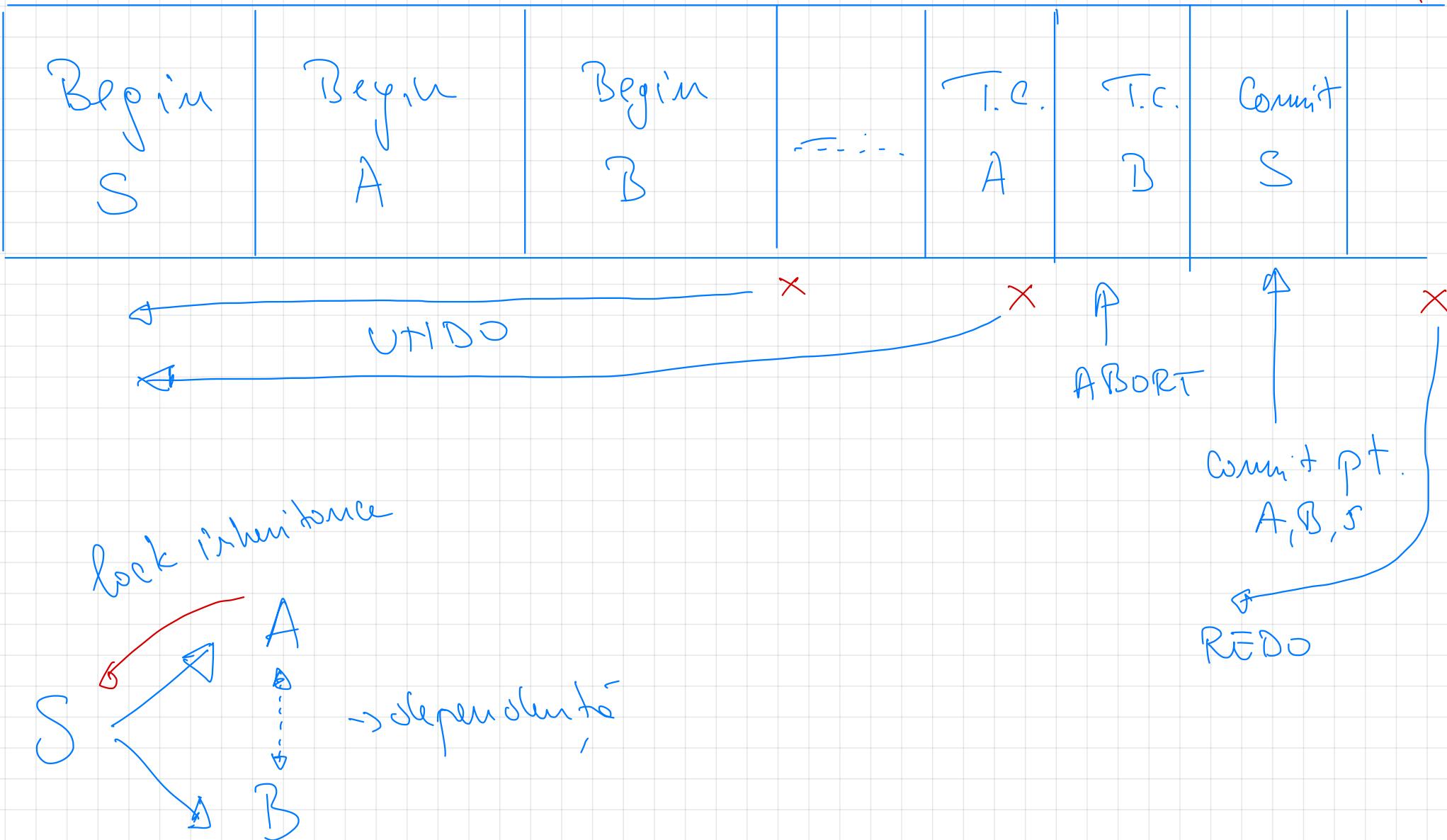
Tentative commit

A t.c.

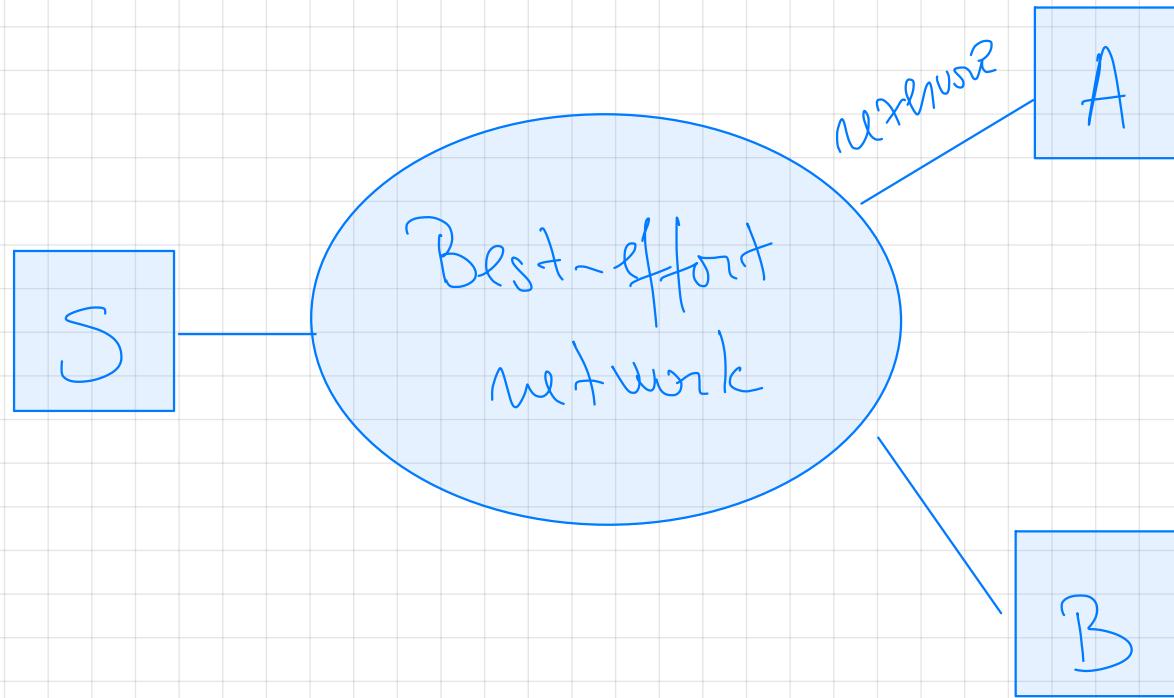
S  
pushing  $\rightarrow$  C.

C t.c.

B pushing --- ABORT

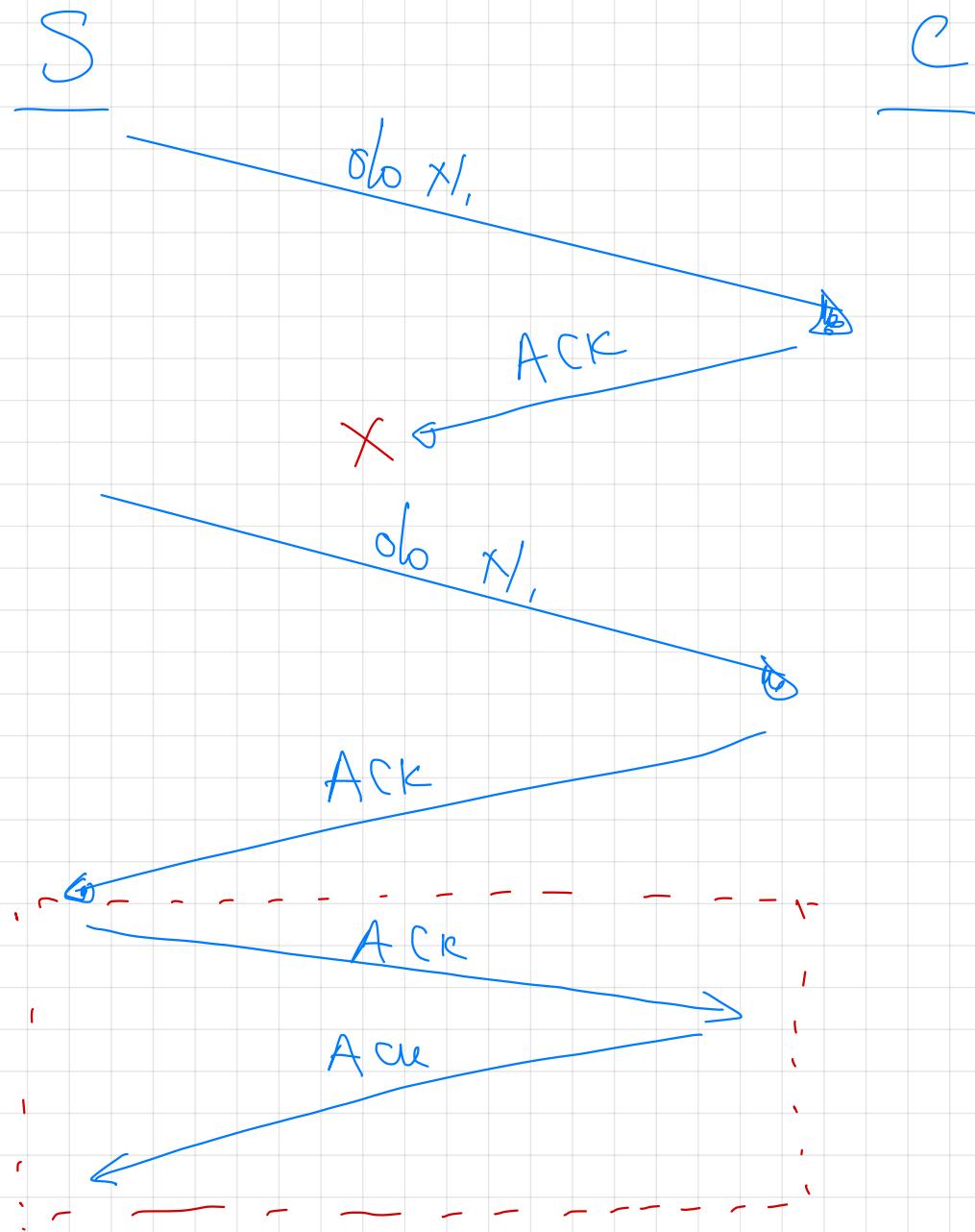


# Control olistribuit

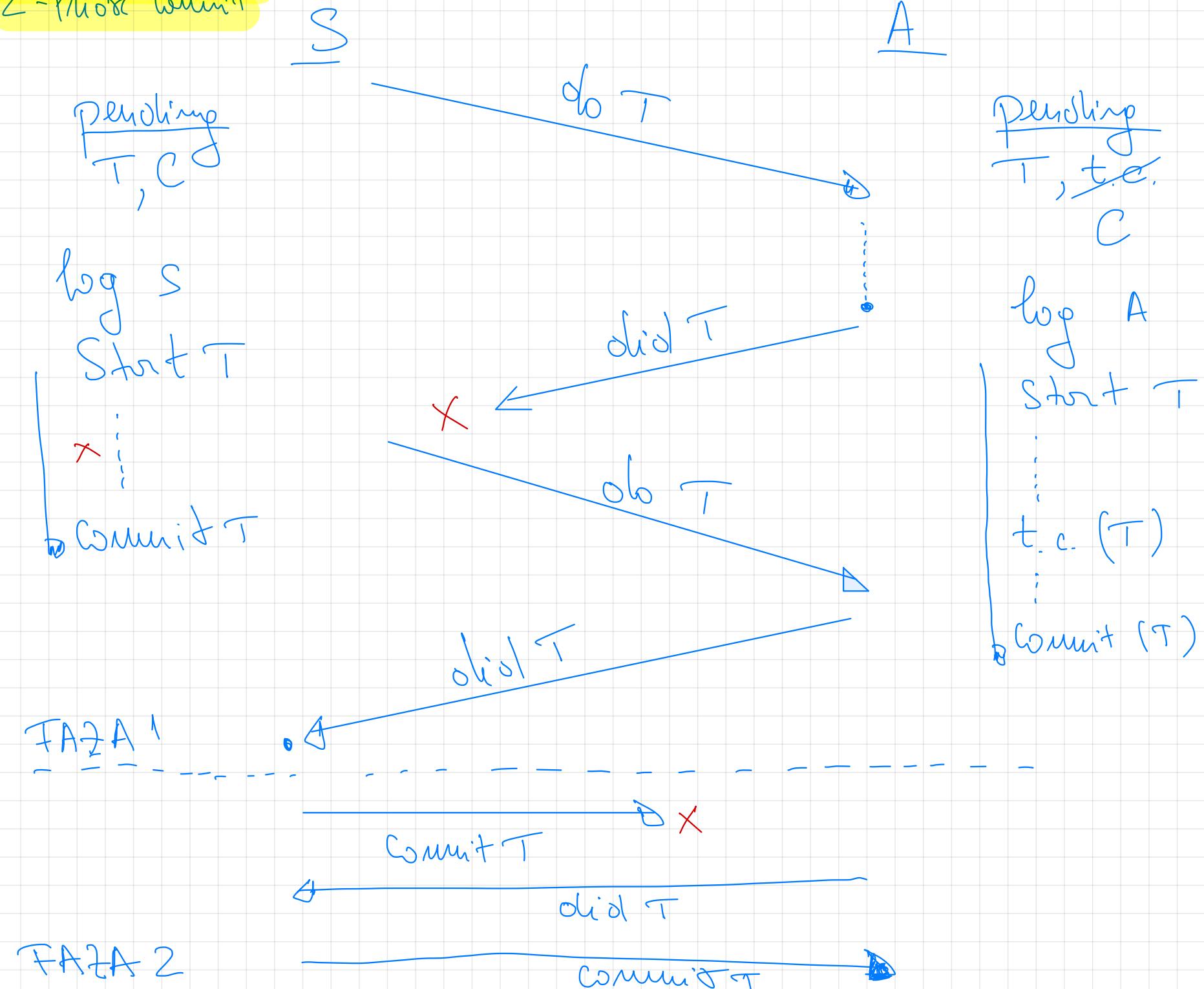


R.P.C.

## Exactly-once RPC



## 2-Phase Commit



## S crash

inainte de Commit

UNDO T, (notifică A?)

după Commit

REDO T, (notifică A?)

## A crash

înainte de T. C.

UNDO A, (S face REDO pt. A)

după T. C.

? → după ce S

## Two-phase Commit

