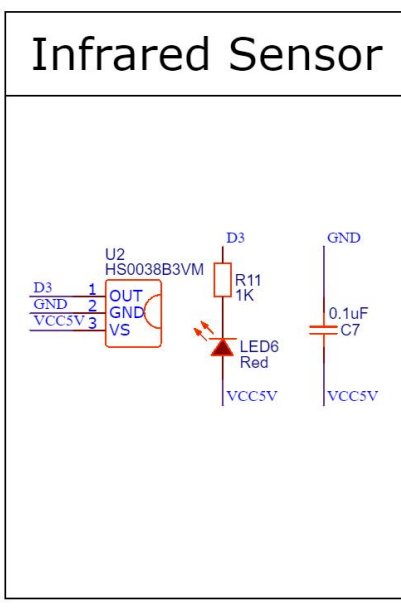
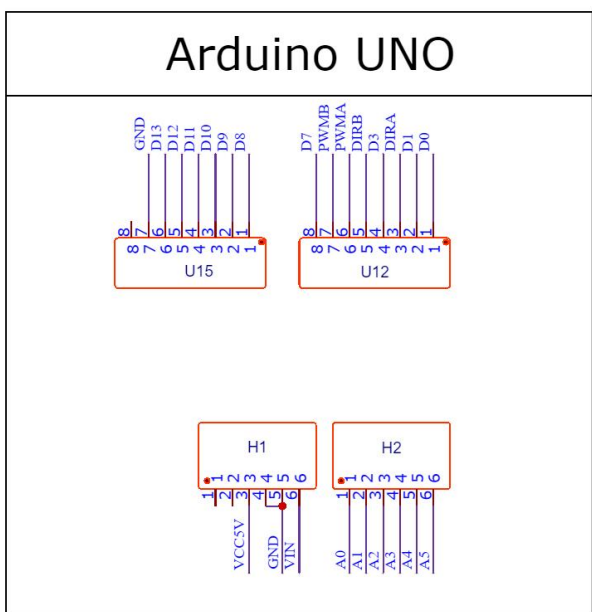
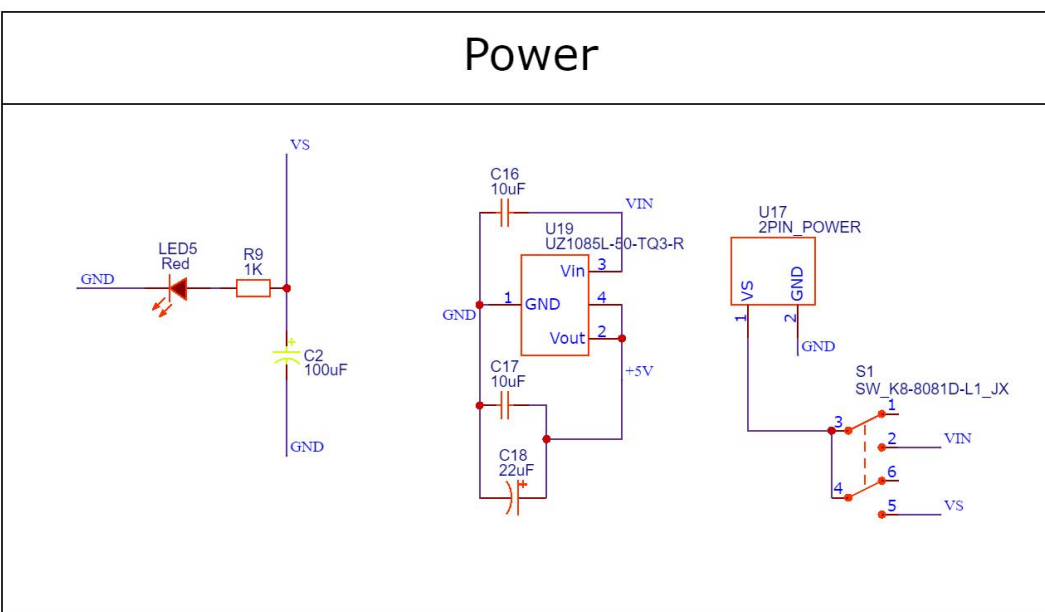
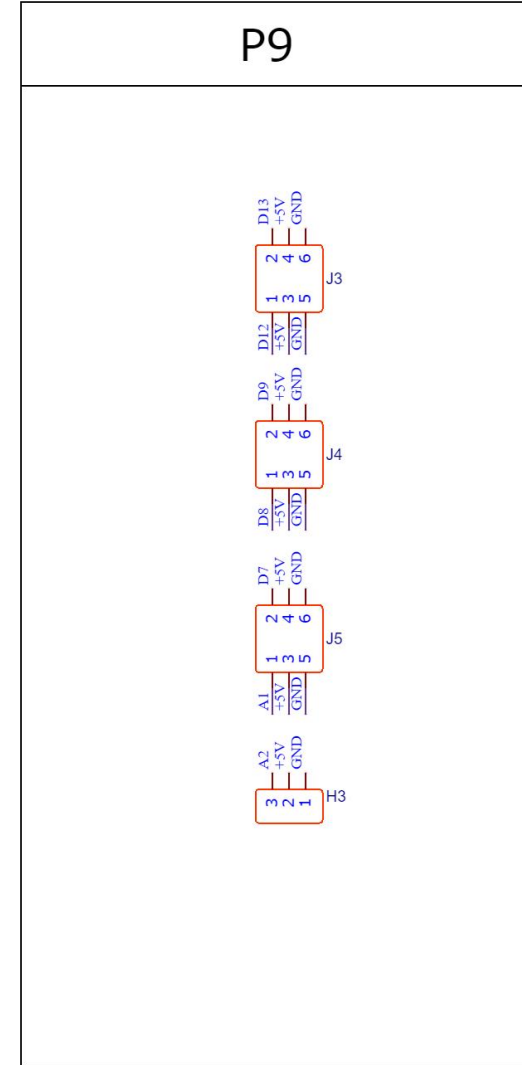
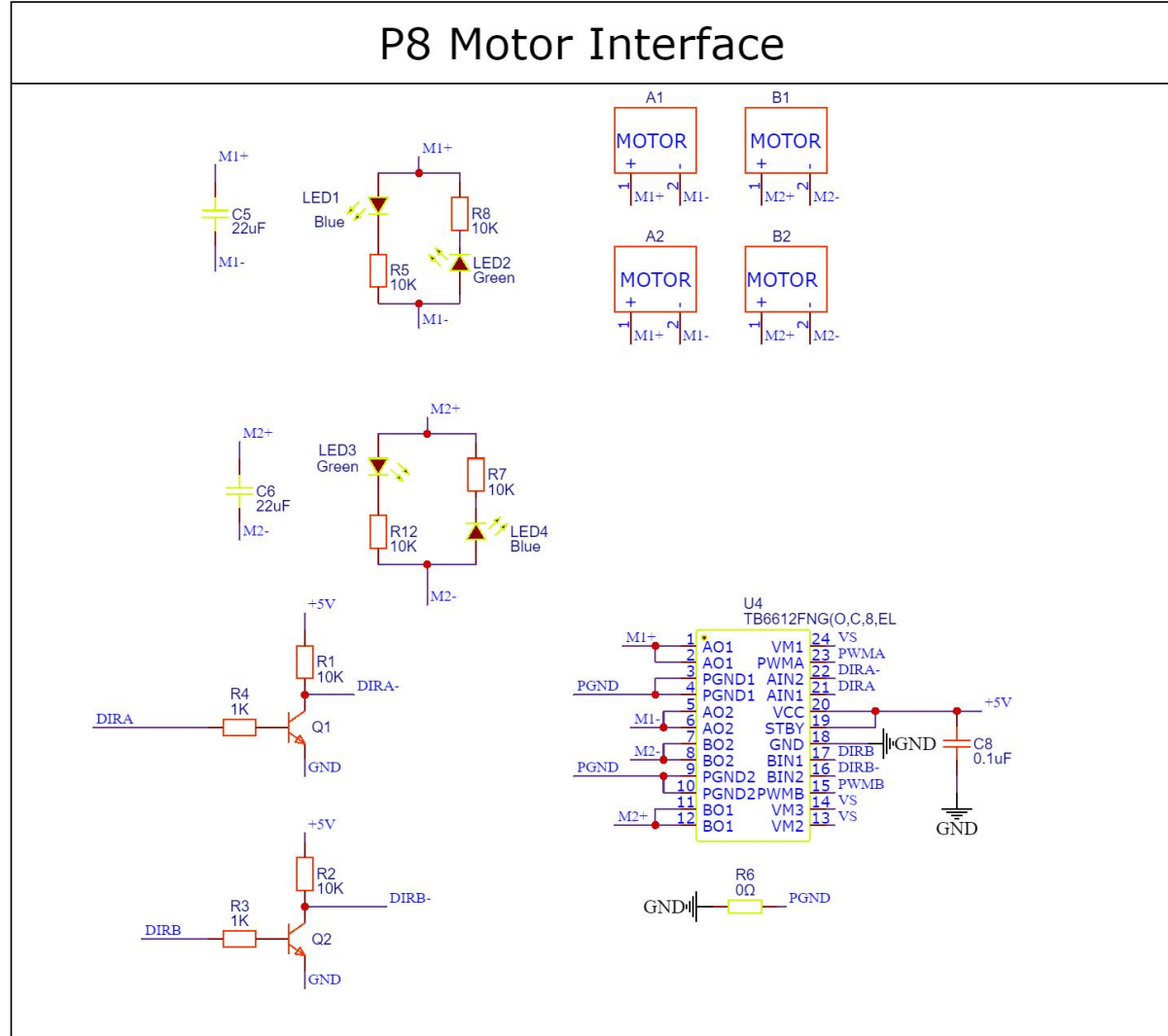
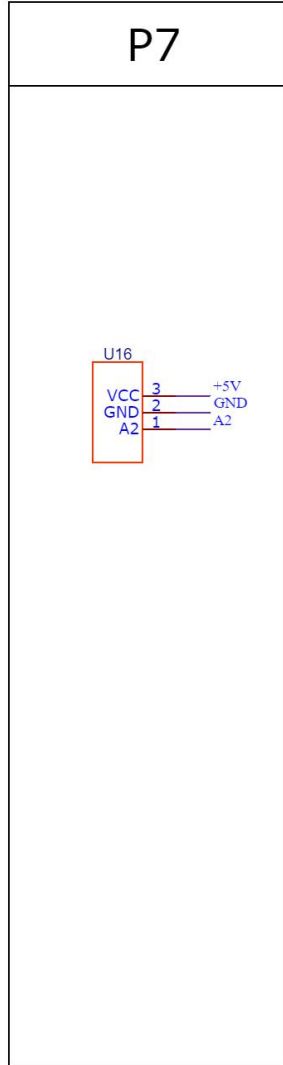
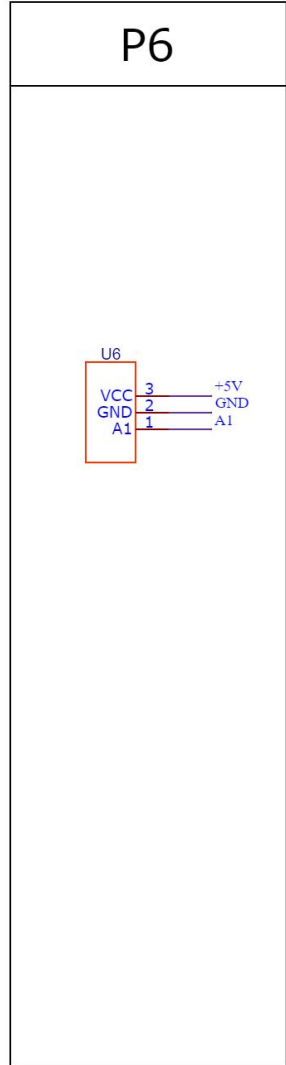
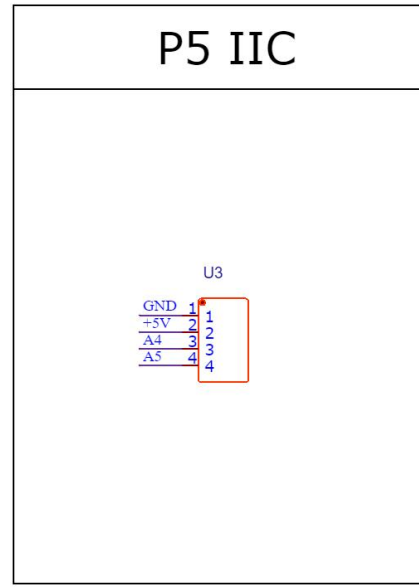
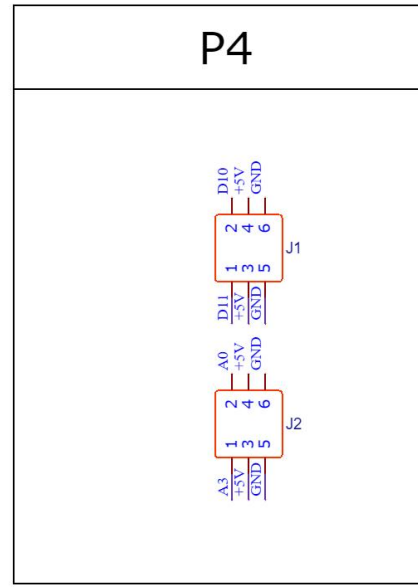
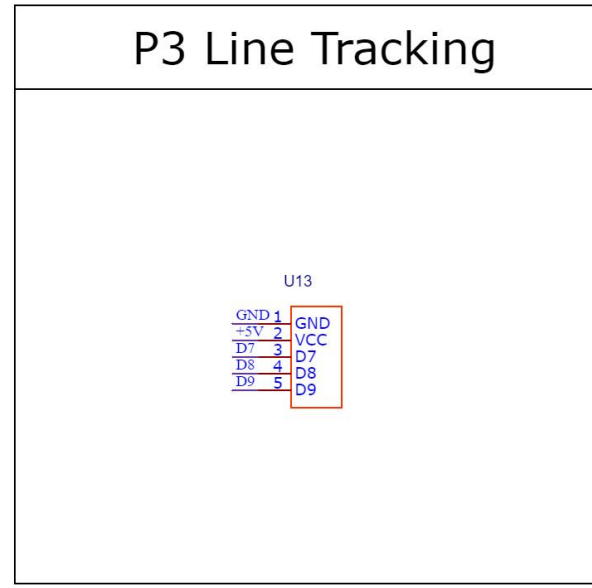
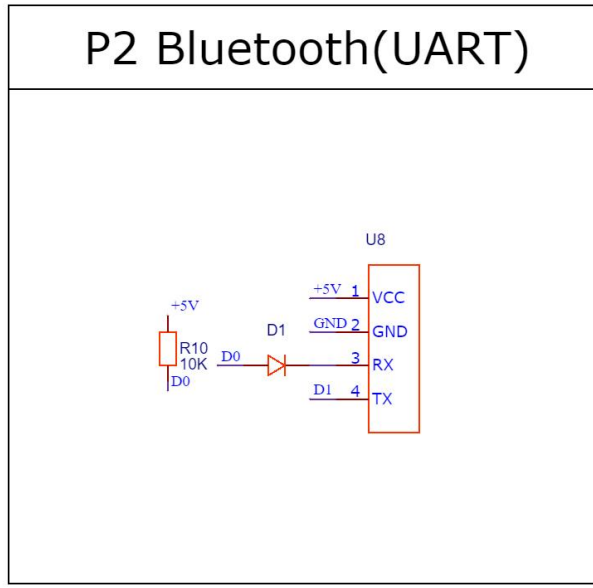
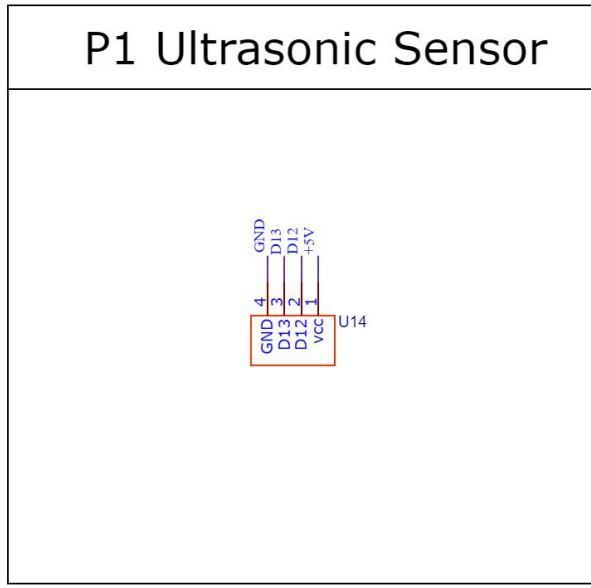


The PWM value is in the range of 0-255. The greater the value, the faster the motors turn. When PWM=0, it means stop, when PWM=255 it means maximum speed.

4WD Robot	D2	D5(PWM)	D4	D6(PWM)
Forward	HIGH	0-255	LOW	0-255
Backward	LOW	0-255	HIGH	0-255
Rotate to left	LOW	0-255	LOW	0-255
Rotate to right	HIGH	0-255	HIGH	0-255
Stop	/	0	/	0



TITLE:	Arduino Motor Driver Shield V2.2 TB6612	REV:	1.0
Company:		Sheet:	1/1
Date:		Drawn By:	