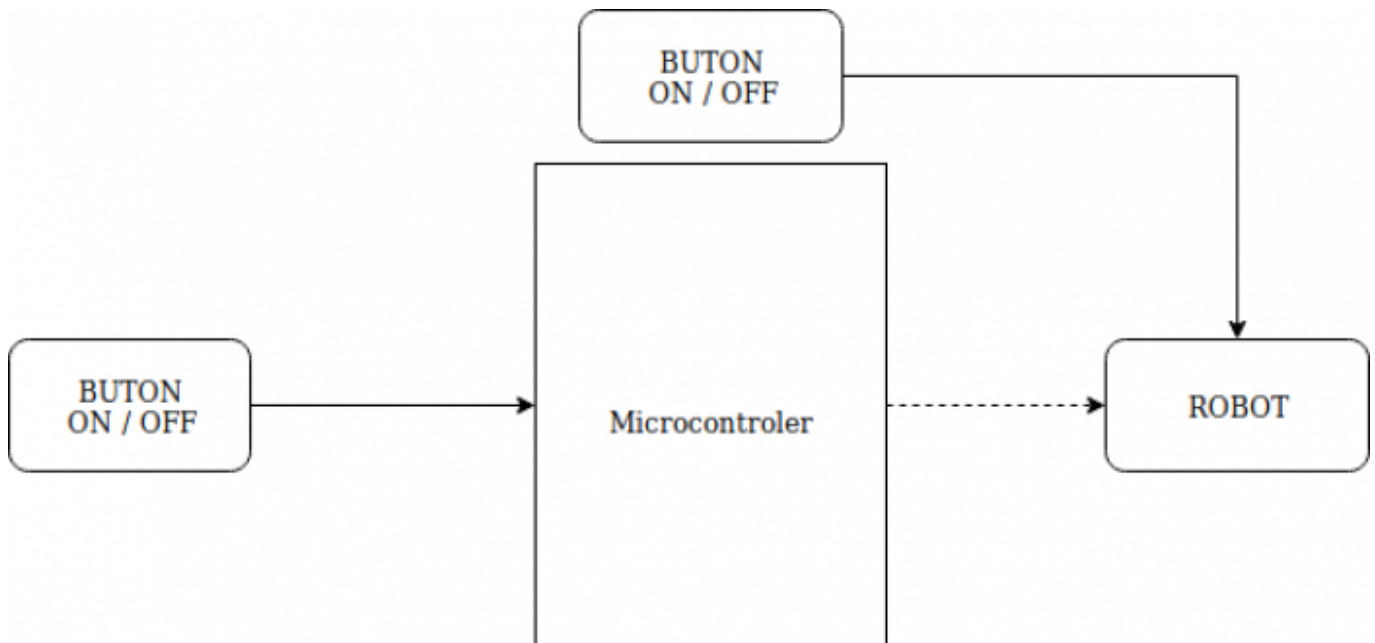


Line Follower Robot

Introducere

Scopul principal al acestui proiect este de a proiecta cat si implementa un robot capabil sa urmareasca o linie si sa se opreasca atunci cand intalneste un anumit simbol specific eventual sa fie capabil sa ocoleasca obstacolele din drum.

Schema bloc



Hardware

Componente

- 2 x DC Gear Motors
- 2 x IR sensor module
- L293D Module
- Wireless Power Source
- Robot Chaises
- Atmega34 Microcontroller IC

16Mhz Crystal Oscillator
2 100nF Capacitors
2 22pF Capacitors
1 Button
Jumper Wires
Breadboard
USBASP v2.0

Utilizare

TODO

Software

TODO

Download

Robo Robo Dodo Bobo [robo.pdf](#)

Referinte

<https://circuitdigest.com/microcontroller-projects/line-follower-robot-using-avr-microcontroller-atmega-16>

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