OVERVIEW

- Internet of Things (IOT)
- Open Standard for IOT
- IOT demands
- OS Design for constrained devices
- \circ Tiny OS
- o Contiki OS
- **RIOT OS**
- NuttX OS
- OS comparisons
- o **Demo**

INTERNET OF THINGS (IOT)

- Internet Connected Objects like RFIDs, Sensors, Actuators, Instruments and smart appliances.
- Context aware communication and computing
- Mainly works with IPv6 rather than IPv4 0
- Powered mainly by Sensor Nodes (Motes) which are low cost, small size \bigcirc and power efficient
- Real Time Guarantee

OPEN STANDARD OF IOT

HTTP, FTP, etc

TCP/UDP/ICMP

BGP, SPF, OLSR

IPv4, IPv6

802.3, 802.11 MAC, DATA Link

IEEE 802.3, 802.11

CoAP

UDP/ICMPv6

IPv6 and RPL

6LoWPAN (IETF Standard)

IEEE 802.15.4 MAC Layer

IEEE 802.15.4 PHY Layer

WHAT DOES IOT DEMAND?

- Low Power, Low Cost and Low memory footprint (RAM and ROM)
- Should have provision for IPv6, with 6LoWPAN Adaptation Layer
- Separate Routing Protocol for Low Power and Lousy networks
- New light Weight Application Layer Protocol unlike http but should have a support for http also
- Header compression for IPv6 against IEEE 802.15.4 MAC

OS DESIGN FOR CONSTRAINED DEVICES

Structure of the Kernel

Monolithic

- Lacks modularity and becomes complex once size exceeds a limit
- Layered Approach
 - Segregation between the kernel mode and user mode

Micro Kernel

This method is preferred as only limited set of tools runs under Kernel Mode and most other drivers and modules runs under User mode which very easy to handle and kernel will not be overloaded.

Programming Model

- No memory segmentation
- Every process runs in its own thread and has its own memory stack

OPERATING SYSTEMS

- TinyOS
- Contiki OS
- **RIOT OS**
- Free RTOS
- NuttX

TINY OS

- Monolithic Kernel
- Uses a programming language nesC
- It provides algorithms, protocols, device drivers, file systems and a shell
- Stopped its support and is not extensively maintained

tinyos.net

CONTIKI OS

- Layered architecture
- Uses C and partial C++ support
- Provides device drivers, communication and sensor data handling as services
- Also comprises uIP Stack, a device driver loader and a Protothreading system
- Protothreads are simple light weight multi threading system that uses a stackless implementation
- Code replacement during runtime

contiki-os.org/

RIOT OS

- Micro Kernel Approach \bigcirc
- Tickless scheduler (It switches to idle thread during idle) 0
- Designed in such a way that the kernel functions are scheduled under a low 0 clock speed.
- Full support of C and C++ is available and partial support of POSIX is ensured
- Full support for RPL, 6LoWPAN, IPv6, TCP, UDP, etc. It's completely modular \bigcirc

riot-os.org

RIOT OS

- Few 100 bytes of RAM and ROM is enough to load the OS into the Motes
- Support multi threading and Real Time
 - through POSIX
 - Zero latency interrupt handlers
 - minimum context switching times
 - the kernel will never crash because of a error prone device drivers

NuttX

- Created by Gregory E. Nutt
- First public release: Feb 2007
- Supports 8 to 32 bits uCs/uPs
- Release under BSD License
- Small footprint
- Very customizable
- Inspiration from Linux/Unix:
 - o VFS
 - o MTD
 - PROCFS
 - NuttShell

nuttx.apache.org

NuttX

- POSIX complaint
- Fully preemptible
- Virtual File System (VFS)
- Loadable kernel modules
- Symmetric Multi-Processing (SMP)
- Realtime scheduling (FIFO, RR, SPORADIC) 0
- Tickless operation support (lower power consumption) 0
- Pseudo-terminals (PTY) and I/O redirection

OS COMPARISONS

OS	TinyOS	Contiki OS	RIOT OS	
Availability	For older Sensors, Mica Family,	For older and Recent Sensors	For all new	
	ATMega, Telosb, etc	like Mica, Telosb,	sensors	
Support	Support has been stopped	Still actively maintained	actively	
Programming	nesC	Partial C	C,C++	
Simulator	TOSSIM	native emulation is available	native method	
RAM,ROM	<1kb, <4kb	<2kb, <30kb	~1.5kb, ~5kb	
Multithreading	No	No (But Protothreads)	Yes	
Modularity	No	Partial Support	Yes	

OS COMPARISONS

OS	Min RAM	Min ROM	C Support	C++ Support	Multi-Threading	MCU w/o MMU	Modularity	Real-Time
Contiki	<2kB	<30kB	0	×	0	1	0	0
Tiny OS	<1kB	<4kB	×	×	0	1	×	×
Linux	~1MB	~1MB	1	1	1	1	0	0
RIOT	~1.5kB	~5kB	1	1	1	1	1	1

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CONTIKI OS DEMO

- Simple Hello World Example
- Simple LED Blinking & Serial Shell Example

A Border Router with IPv6 and RPL Demo

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