AI & ML for IoT Systems

Why AI + IoT Now



Billions of connected sensors



Cheap compute at the edge



Real-time decisions are expected



Al turns raw telemetry into value

IoT Stack Overview



Perception layer: sensors, actuators



Network layer: connectivity + routing



Application layer: analytics, automation, Al



Feedback/control loop

From Raw Signals to Usable Data

Sampling rate & Nyquist

Quantization and compression

Denoising, normalization

Time sync across devices

Control and Actuation Loops



Sense \rightarrow infer \rightarrow act



Closed-loop autonomy (e.g. smart HVAC)



Latency budgets: ms vs seconds



Safety and fail-safes

Feature Engineering for Sensor Data

- Windowing (fixed, sliding, adaptive)
- Stats: mean, variance, kurtosis
- Frequency domain: FFT, spectrograms
- Domain features: vibration signatures

Why ML in IoT?

- Predictive maintenance
- Activity / gesture recognition
- Occupancy-aware energy optimization
- Anomaly detection in industrial systems
- Autonomous navigation / robotics

Edge vs Cloud vs Hybrid



Edge: instant response, local context



Cloud: heavy analytics, global context

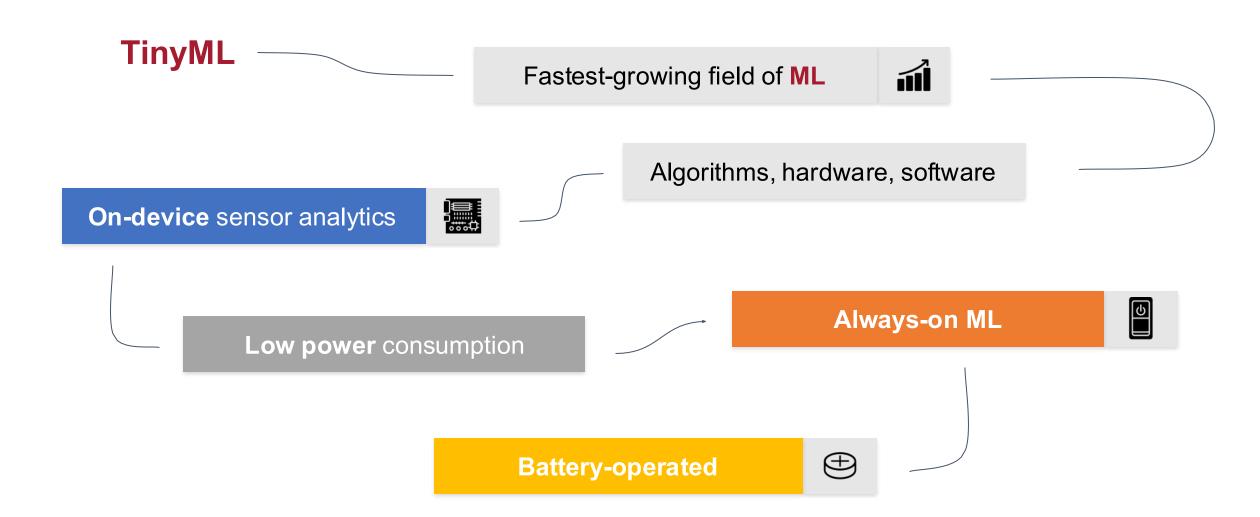


Hybrid: edge pre-filter + cloud refinement



Cascade inference patterns

What is Tiny Machine Learning (TinyML)?



Why Edge Intelligence?

- Privacy: data stays local
- Low latency: sub-100 ms actuation
- Reliability offline / flaky network
- Bandwidth savings: send insights, not raw video

Edge Hardware Landscape



MCUs (tens of kB RAM)



Single-board computers (Raspberry Pi class)

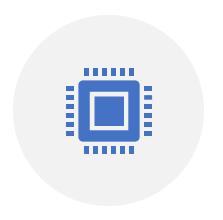


NPUs / TPUs / accelerators

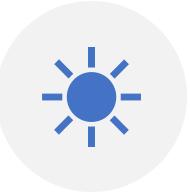


Battery and thermal limits

TinyML Concepts







ML ON ULTRA-LOW-POWER MICROCONTROLLERS

USE CASES: WAKE-WORD, GESTURE, LEAK DETECTION

ALWAYS-ON SENSING UNDER ~1 MW BUDGET

Reference AloT Architecture



Sensor node



Gateway / edge aggregator



Cloud analytics / data lake



Digital twin / dashboard



Human-in-theloop feedback

EdgeML (Pt)

Autonomous Car Control



Image Recognition



TinyML (P↓)

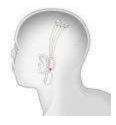
KeyWord Spotting





Motion & biometric





Environmental Control



Image Spot



TinyML Application Areas













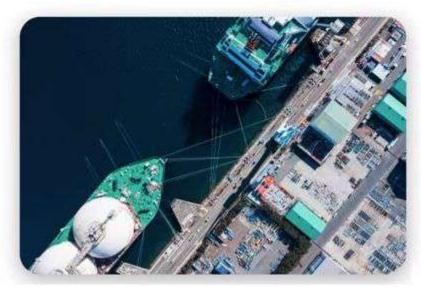
Predictive Maintenance



Motion, current, audio and camera

- → Industrial
- → White goods
- → Infrastructure
- → Automotive

Asset Tracking & Monitoring



Motion, temp, humidity, position, audio and camera

- → Logistics
- → Infrastructure
- → Buildings

Human & Animal Sensing



Motion, radar, audio, PPG, ECG

- → Health
- → Consumer
- → Industrial



Hardware

EdgeML













Image Classification 250 KB+

KeyWord Spotting Audio Classification 50 KB





TinyML

Anomaly Detection Sensor Classification 20 KB



Rpi-Pico (Cortex-M0+)



Arduino Nano (Cortex-M4)



Arduino Pro (Cortex-M7)

Video Classification 2 MB+ **Object Detection** Complex Voice



Processing 1 MB+













RaspberryPi (Cortex-A)



SmartPhone

Jetson Nano (Cortex-A + GPU)

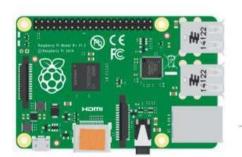




Train a model

Convert model Optimize model

Deploy model at Edge Make inferences at Edge









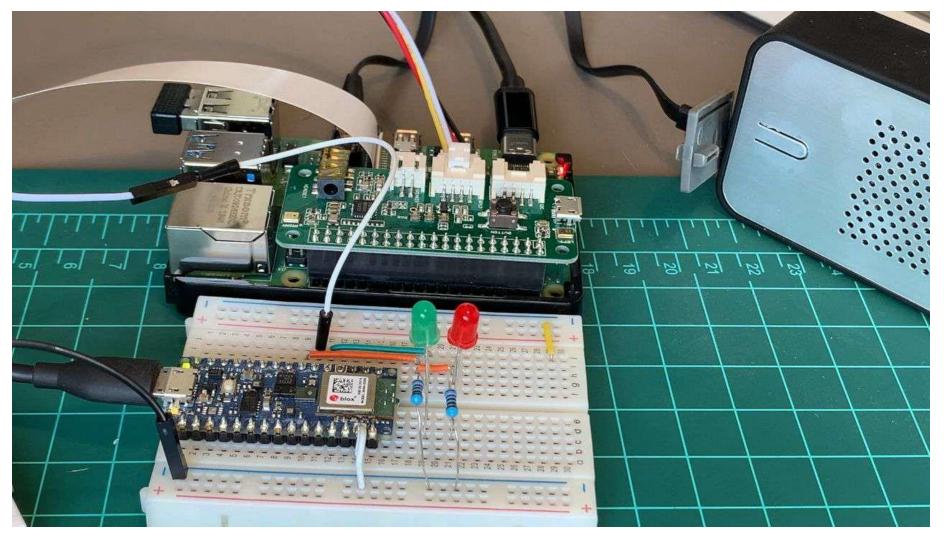






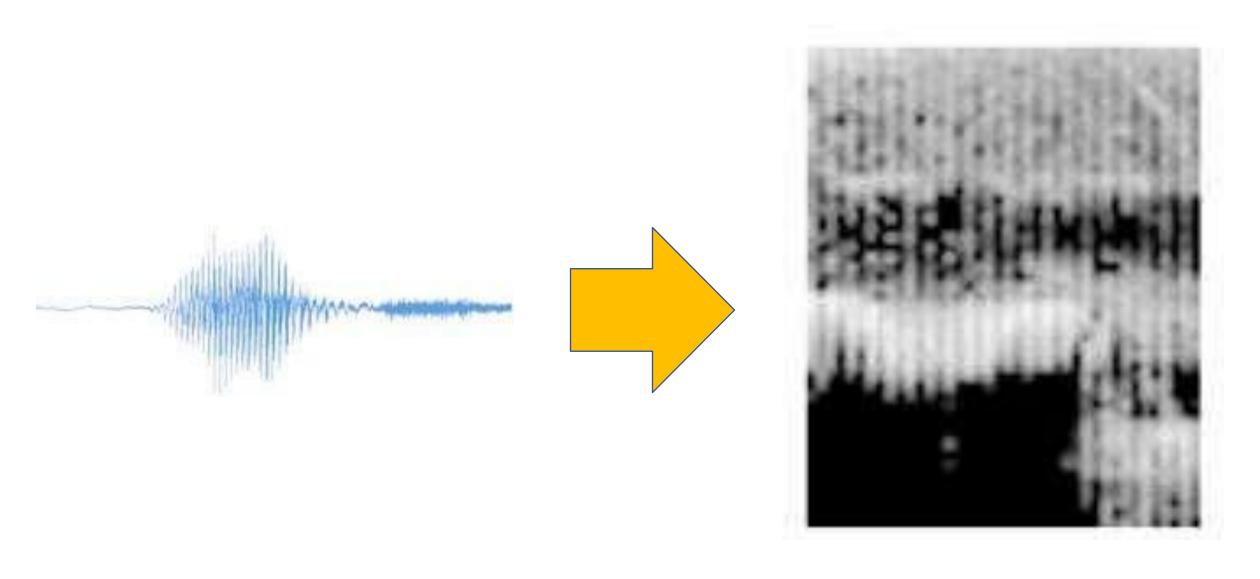
Microcontroller

Example: KeyWord Spotting (KWS)



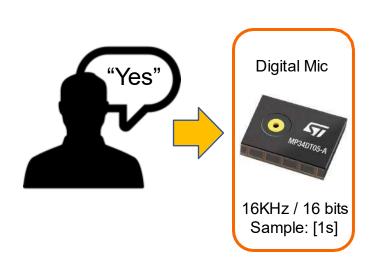


https://mjrobot.org/2021/01/27/building-an-intelligent-voice-assistant-from-scratch/

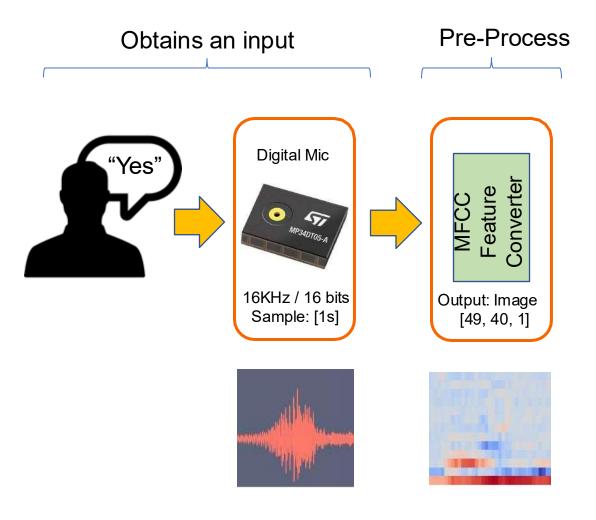


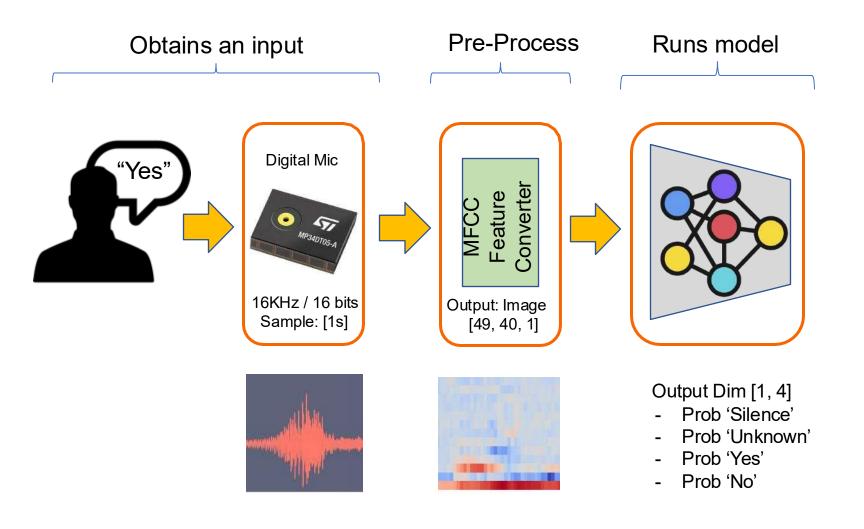
Sound Image

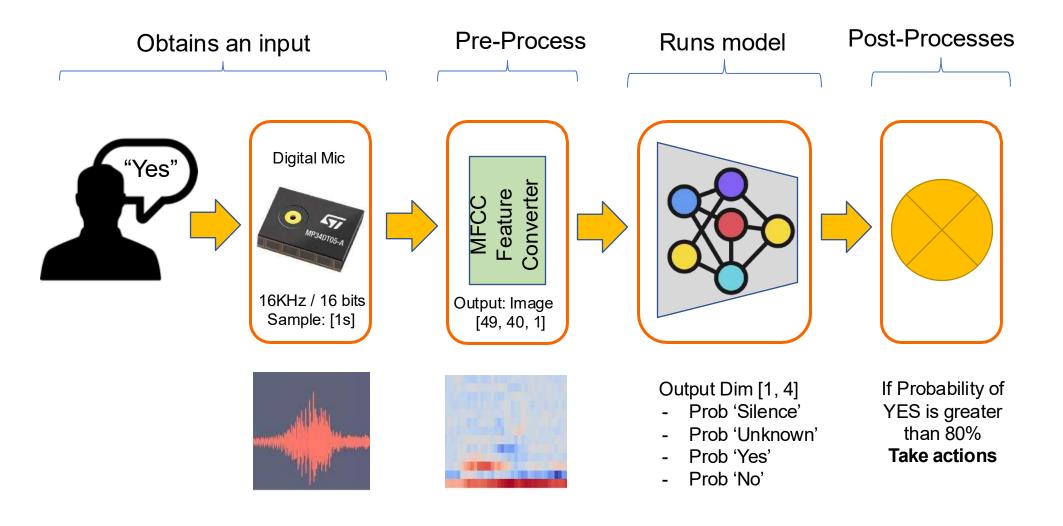
Obtains an input

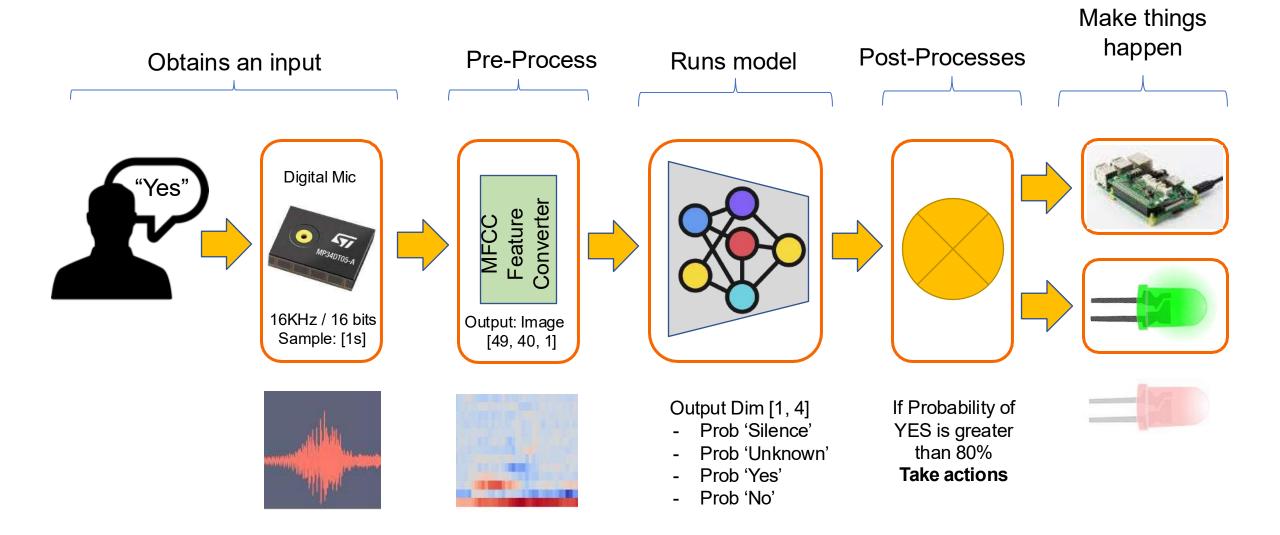




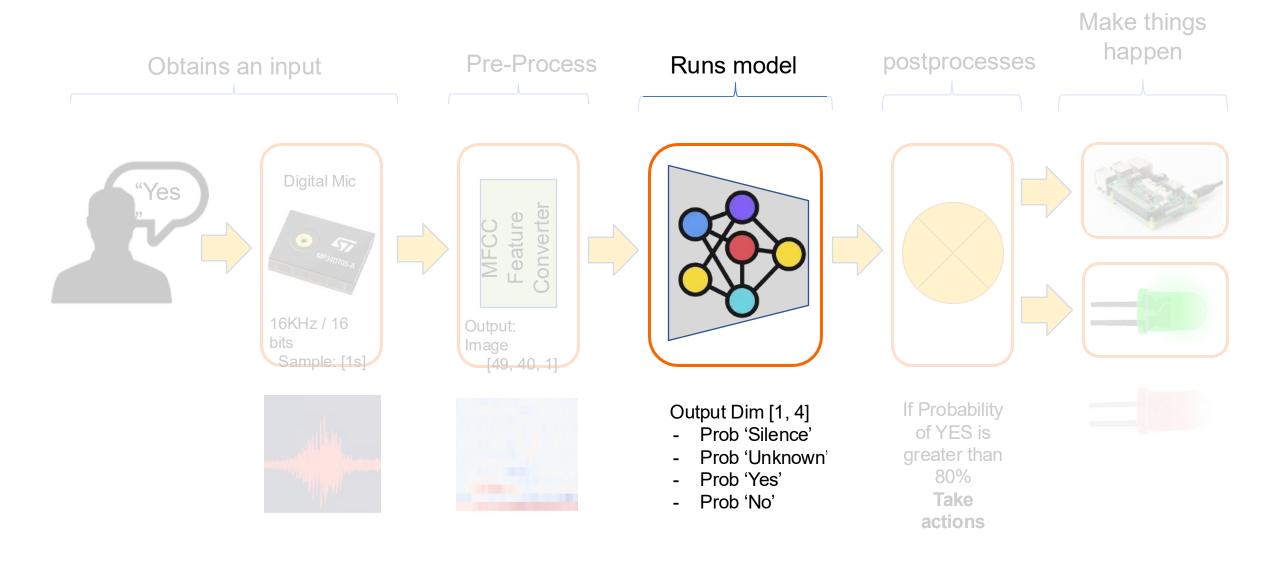




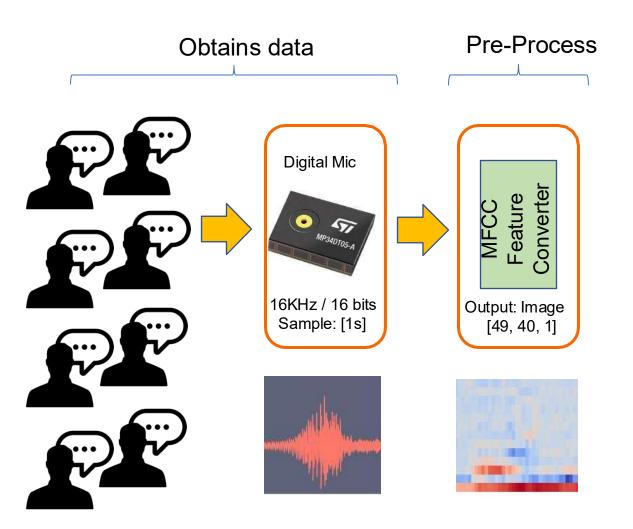




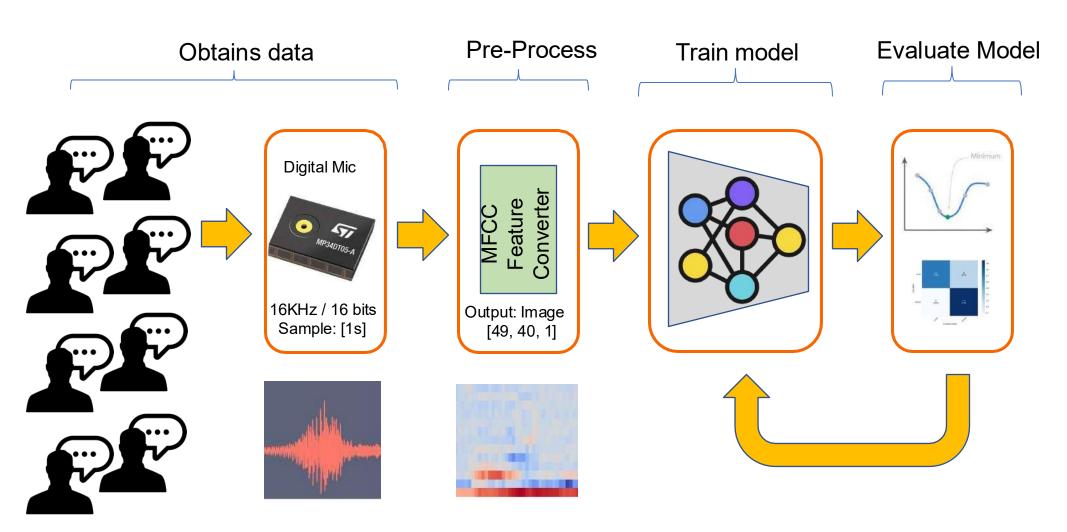
KeyWord Spotting (KWS) - Model



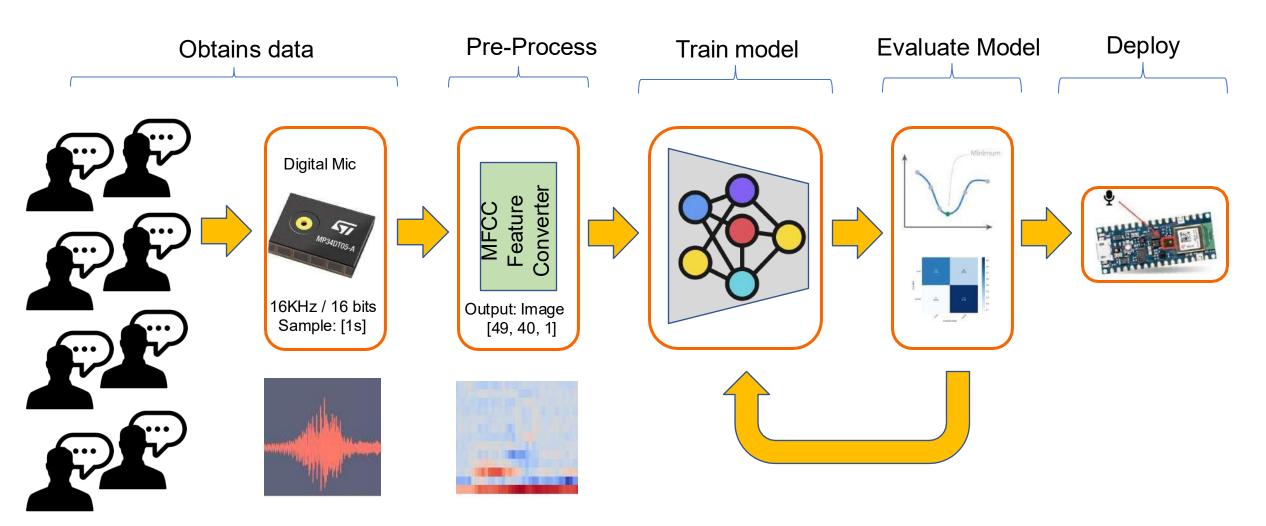
KeyWord Spotting (KWS) – Create Model (Training)



KeyWord Spotting (KWS) - Create Model (Training)



KeyWord Spotting (KWS) - Create Model (Training)



Supervised Learning Refresher

- Regression vs classification
- Temporal train/val/test splits matter
- Labeling is expensive and noisy
- Concept drift over time

Supervised Learning

- Majority of practical ML uses supervised learning
- Mapping function approximated from past experience
 - Regression f(x)=y, y is a real number
 - Classification f(x)=y, y is a category label
- Training
 - Labeled positive and negative examples
 - From unseen input predict corresponding output
 - Learning until acceptable performance is achieved

Unsupervised & Self-Supervised IoT



Clustering for behavior patterns



Autoencoders for anomaly detection



Contrastive learning on time windows



Few/zero-label environments

Unsupervised Learning

- Discover hidden relations and learn about the data
 - Clustering $f(X) = [X_1, ..., X_k]$, k disjoint subsets
 - Association $f(X_i, X_i) = R$, relation
- Training
 - All examples are positive
 - No labeling, no teacher
 - No single correct answer
- Practical usage
 - Derive groups, not explicitly labeled
 - Market basket analysis (association among items)

Time Series Modeling Approaches



Classical: ARIMA, Kalman filters



ML: Random Forests on engineered windows



Deep: RNN / LSTM / GRU / 1D CNN



Transformers for long context

Activity Recognition Example

- Input: accelerometer / gyroscope
- Sliding window segmentation
- Feature extraction vs end-to-end deep model
- Output: walk / run / fall / idle
- Use case: elder fall detection

Predictive Maintenance Example

- Vibration + temperature from motors
- Estimate Remaining Useful Life (RUL)
- Early fault signatures are subtle
- Class imbalance: failures are ~0.1%
- Metric: precision at very low false alarms

Anomaly Detection in IoT

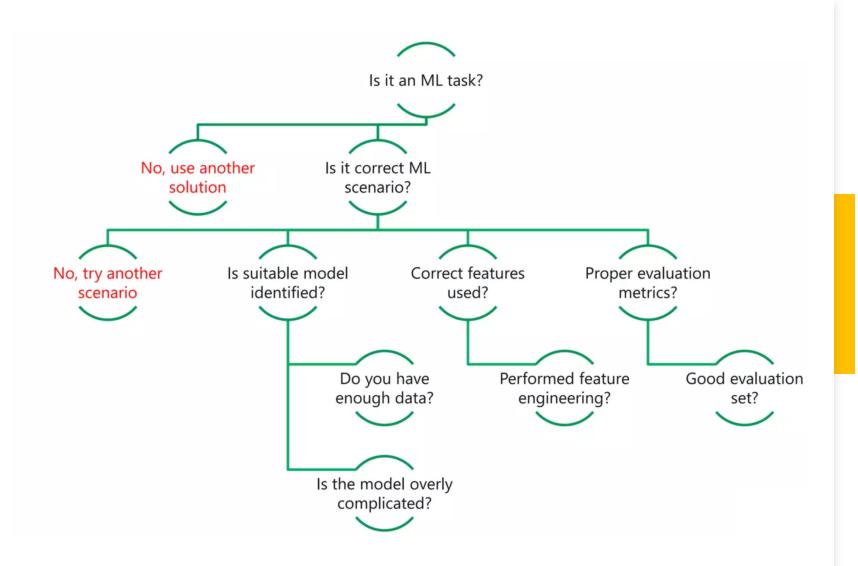
- Why anomalies matter: safety, cost, security
- Thresholding simple stats
- Isolation Forest / density methods
- Autoencoder reconstruction error
- Online streaming anomaly scores

Computer Vision in IoT

- Smart cameras: traffic, quality inspection
- Object detection, pose estimation
- PPE compliance / safety zones
- Privacy: blur faces, process on-device

Multimodal Sensor Fusion

- Fusing IMU + camera + GPS + audio
- Early fusion vs late fusion
- Attention-based fusion architectures
- Robustness if one sensor drops



ML Decision Tree

Diagnose Steps (part 1)

- 1. Is it a ML task? Are you sure ML is the best solution?
 - Hard: X is independent of Y: X<name, age, income>, Y = height
 - Easy: X is a set with limited variations. Configure Y = F(X)
- 2. Appropriate ML scenario?
 - Supervised learning classification, regression, anomaly detection)
 - Unsupervised learning (clustering, pattern learning)
- 3. Appropriate model?
 - Data size (small data -> linear model, large data -> consider nonlinear)
 - Sparse data (require normalization to perform better)
 - Imbalanced data (special treatment of the minority class required)
 - Data quality (noise and missing values require loss function)
- 4. Enough training data?
 - Investigate how precision improves with more data

Diagnose Steps (part 2)

5. Model overly complicated?

- Start simple first, increase complexity and evaluate performance
- Avoid overfitting to training set

6. Feature quality

- Have you identified all useful features?
- Use domain knowledge of an expert to start
- Include any feature that could be found and investigate model performance

7. Feature engineering

- The best strategy to improve performance and reveal important input
- Encode features, normalize [0:1], combine features

8. Combine models

- If multiple models have similar performance there is a chance of improvement
- Use one model for one subset of data and another model for the other

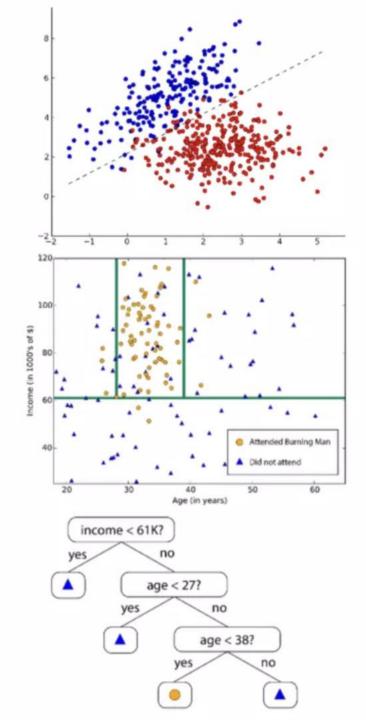
Diagnose Steps (part 3)

9. Model validation

- Use appropriate performance indicator (accuracy, precision, recall, F1, etc.)
- How well does the model describe data? (AUC)
- Data typically divide into Training and Validation
- Evaluate accuracy on disjoint dataset (other than training dataset)
- Tune model hyper parameters (i.e. number of iterations)

Types of Algorithms

- Linear Algorithms
 - Classification classes separated by straight line
 - Support Vector Machine wide gap instead of line
 - Regression linear relation between variables and label
- Non-Linear Algorithms
 - Decision Trees and Jungles divide space into regions
 - Neural Networks complex and irregular boundaries
- Special Algorithms
 - Ordinal Regression ranked values (i.e. race)
 - Poisson discrete distribution (i.e. count of events)
 - Bayesian normal distribution of errors (bell curve)

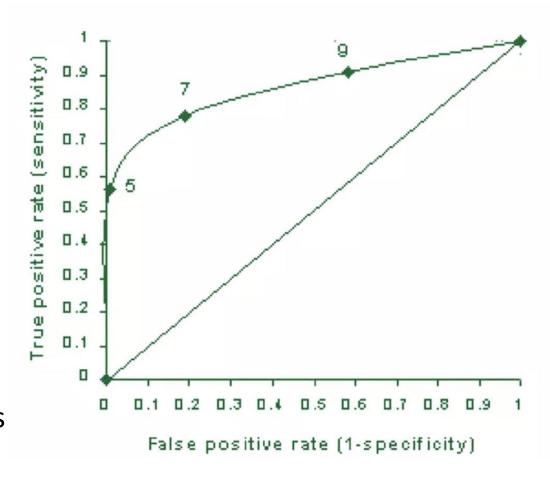


Model Performance (Classification)

- Binary classification outcomes {positive; negative}
- ROC curve
 - TP Rate = True Positives / All Positives
 - FP Rate = False Positives / All Negatives
- Example:

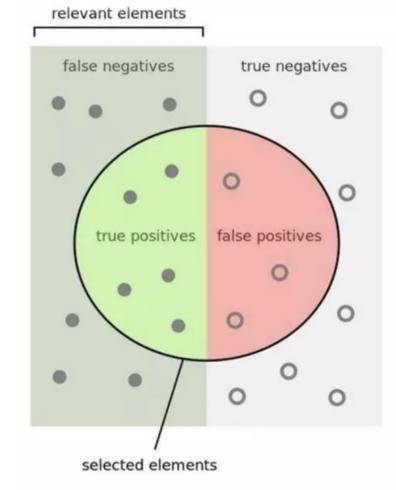
	TP Rate	FP Rate	1-FP Rate
5	0.56	0.99	0.01
7	0.78	0.81	0.19
9	0.91	0.42	0.58

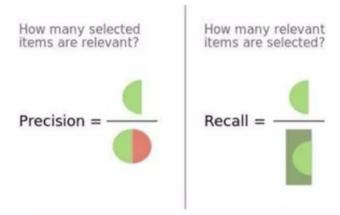
- AUC (Area Under Curve)
 - KPI for model performance and comparison
 - 0.5 = random prediction, 1 = perfect match
- For Multiclass average from all RoC curves



Threshold Selection (Binary)

- Probability Threshold
 - Cost of one error could be much higher than cost of other
 - E.g. spam filter it is more expensive to miss a real mail
- Accuracy
 - For symmetric 50/50 data
- Precision
 - E.g. 1000 devices, 5 fails, 8 predicted, 4 true failures
 - Correct positives (e.g. 4/8 = 0.5, FP are expensive)
- Recall
 - Correctly predicted positives (e.g. 4/5=0.8, FN are expensive)
- F1(balanced error cost)
 - Balanced cost of Precision/Recall





Model Performance (Regression)

- Coefficient of Determination (R²)
 - Single numeric KPI how well data fits model
 - $R^2 > 0.6 good$, $R^2 > 0.8 very good$, $R^2 = 1 perfect$
- Mean Absoute Error (MAE) / Root Mean Squared Error
 - Deviation of estimates from observed real values
 - Compare model errors measure in the SAME units
- Relative Absolute Error Relative Squared Error
 - % deviation from real value
 - Compare model errors measure in the DIFFERENT units

Evaluation Metrics for IoT ML

- Latency (ms)
- Power draw (mW)
- Model size / memory footprint
- False alarm vs miss cost
- Closed-loop control stability

Model Compression Techniques

- Quantization (8-bit, 4-bit)
- Pruning weights / neurons
- Knowledge distillation
- Neural architecture search for low FLOPs

On-Device Inference Pipeline

- Capture → preprocess → inference → decision
- Memory budgeting for buffers + weights
- Real-time scheduling with firmware tasks
- Interrupt-driven ML (e.g. wake word)

Federated Learning for IoT

- Devices train locally on private data
- Only model updates are shared
- Benefits: personalization + privacy
- Challenges: non-IID data, stragglers

Digital Twins

- Virtual replica of a physical asset
- Live sync with sensor data
- Simulate 'what if' scenarios
- Uses: predictive maintenance, optimization

Privacy & Responsible AI in IoT

- Always-on sensing = surveillance risk
- Behavior inference from 'harmless' signals
- Data minimization and edge filtering
- Transparency + consent for end users

Regulatory & Compliance

- Safety standards for industrial monitoring
- Data protection (GDPR-style thinking)
- Al accountability + audit trails
- Explainability for automated decisions

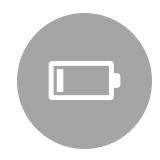
LLMs + IoT

- Natural language interfaces ('Why did the alarm trigger?')
- Edge copilots for technicians
- Summarizing fleets of sensor logs
- Risk: hallucination in safety-critical loops

Energy-Aware Intelligence



Adaptive sampling / duty cycling



Battery-aware model selection



Green AI: minimize inference carbon cost



Sustainability as design constraint

Edge Swarms & Collective Intelligence



Many small devices collaborating locally



Gossip instead of central cloud



Distributed anomaly detection



Use cases: env monitoring, precision agriculture

Where This Field Is Going



Every sensor becomes intelligent



Every decision must be explainable



AI/ML is the differentiator in IoT



Your job: design systems that are smart, safe, and trustworthy